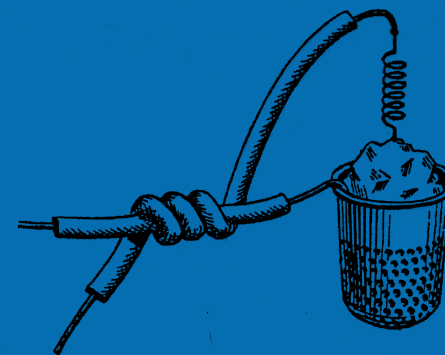
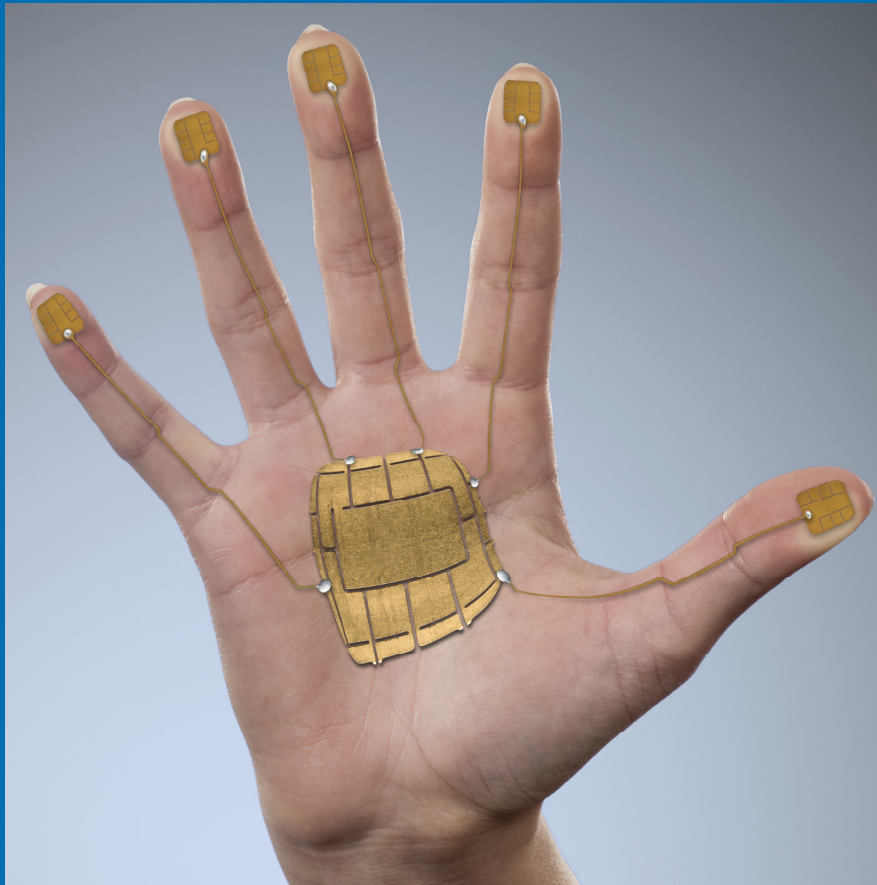


# SENSOR DEVICES



# OUTLINE

- **Planning**
- **Lecture 1**
  - **1 Classification and terminology of sensors**
  - **2 Semiconductor Sensor Technologies**
- **Lecture 2**
  - **2 Semiconductor Sensor Technologies (cont.)**

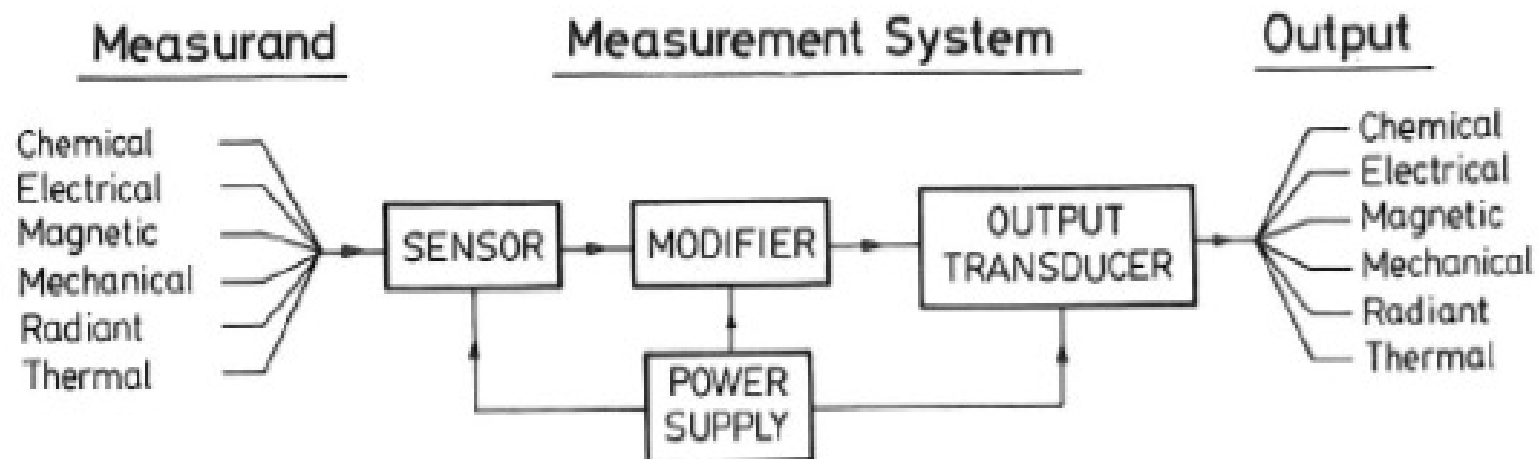
# COURSE ACTIVITIES

- 10 LECTURES
- LABORATORY WORK, WRITTEN REPORTS
  - Attend scheduled class!
  - Trondheim students have local laboratory work, HIST is responsible
- WRITTEN EXAM IN JANUARY
- ISBN 0-471-54609-7 "Semiconductor sensors" S.M.Sze
- <http://apachepersonal.miun.se/~bornor/sensor/>

# LECTURE PLAN

- L1 CLASSIFICATION AND TERMINOLOGY OF SENSORS
- L2 SEMICONDUCTOR SENSOR TECHNOLOGIES
- L3 ACOUSTIC SENSORS
- L4 MECHANICAL SENSORS
- L5 MAGNETIC SENSORS
- L6 RADIATION SENSORS
- L7 THERMAL SENSORS
- L8 CHEMICAL SENSORS
- L9 BIOSENSORS AND INTEGRATED SENSORS

# CLASSIFICATION AND TERMINOLOGY OF SENSORS



THE SENSOR PRODUCE IN MOST CASE AN ELECTRICAL SIGNAL

**TABLE 1 Measurands<sup>5</sup>**

---

**1. Acoustic**

- 1.1 Wave amplitude, phase, polarization, spectrum
- 1.2 Wave velocity
- 1.3 Other (specify)

**2. Biological**

- 2.1 Biomass (identities, concentrations, states)
- 2.2 Other (specify)

**3. Chemical**

- 3.1 Components (identities, concentrations, states)
- 3.2 Other (specify)

**4. Electric**

- 4.1 Charge, current
- 4.2 Potential, potential difference
- 4.3 Electric field (amplitude, phase, polarization, spectrum)
- 4.4 Conductivity
- 4.5 Permittivity
- 4.6 Other (specify)

**5. Magnetic**

- 5.1 Magnetic field (amplitude, phase, polarization, spectrum)
- 5.2 Magnetic flux
- 5.3 Permeability
- 5.4 Other (specify)

**6. Mechanical**

- 6.1 Position (linear, angular)
- 6.2 Velocity
- 6.3 Acceleration
- 6.4 Force
- 6.5 Stress, pressure
- 6.6 Strain
- 6.7 Mass, density
- 6.8 Moment, torque
- 6.9 Speed of flow, rate of mass transport
- 6.10 Shape, roughness, orientation
- 6.11 Stiffness, compliance
- 6.12 Viscosity
- 6.13 Crystallinity, structural integrity
- 6.14 Other (specify)

**7. Optical**

- 7.1 Wave amplitude, phase, polarization, spectrum
- 7.2 Wave velocity
- 7.3 Other (specify)

**8. Radiation**

- 8.1 Type
- 8.2 Energy
- 8.3 Intensity
- 8.4 Other (specify)

**9. Thermal**

- 9.1 Temperature
- 9.2 Flux
- 9.3 Specific heat
- 9.4 Thermal conductivity
- 9.5 Other (specify)

**10. Other (specify)**

---

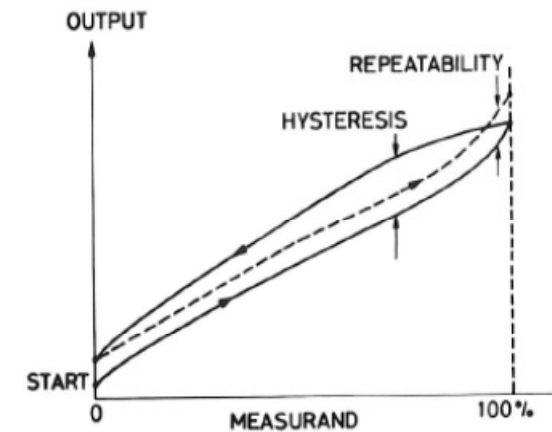
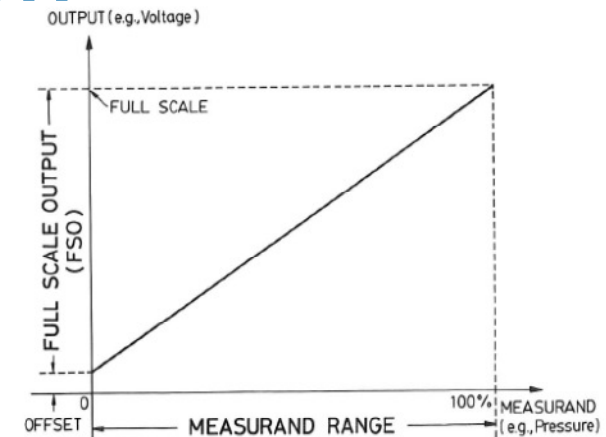
**TABLE 2 Technological Aspects, Detection Means and Conversion Phenomena of Sensors<sup>5</sup>**

Technological Aspects	Detection Means	Conversion Phenomena
1. Ambient conditions allowed	1. Biological	1. Biological
2. Full-scale output	2. Chemical	1.1 Biochemical transformation
3. Hysteresis	3. Electric, magnetic, or electromagnetic wave	1.2 Physical transformation
4. Linearity	4. Heat, temperature	1.3 Effects on test organism
5. Measured range	5. Mechanical displacement or wave	1.4 Spectroscopy
6. Offset	6. Radioactivity, radiation	1.5 Others (specify)
7. Operating life	7. Others (specify)	2. Chemical
8. Output format		2.1 Chemical transformation
9. Overload characteristics		2.2 Physical transformation
10. Repeatability		2.3 Electrochemical process
11. Resolution		2.4 Spectroscopy
12. Selectivity		2.5 Others (specify)
13. Sensitivity		3. Physical
14. Speed of response		3.1 Thermoelectric
15. Stability		3.2 Photoelectric
16. Others (specify)		3.3 Photomagnetic
		3.4 Magnetoelectric
		3.5 Elastomagnetic
		3.6 Thermoelastic
		3.7 Elastoelectric
		3.8 Thermomagnetic
		3.9 Thermo-optic
		3.10 Photoelastic
		3.11 Others (specify)

# SENSOR CHARACTERIZATION

- Hysteresis
- Linearity
- Measurand Range
- Offset
- Operating Life
- Output Format
- Overload Characteristics
- Repeatability
- Resolution
- Selectivity
- Sensitivity
- Speed of Response
- Stability

Ambient Conditions Allowed  
Full Scale Output (FSO)



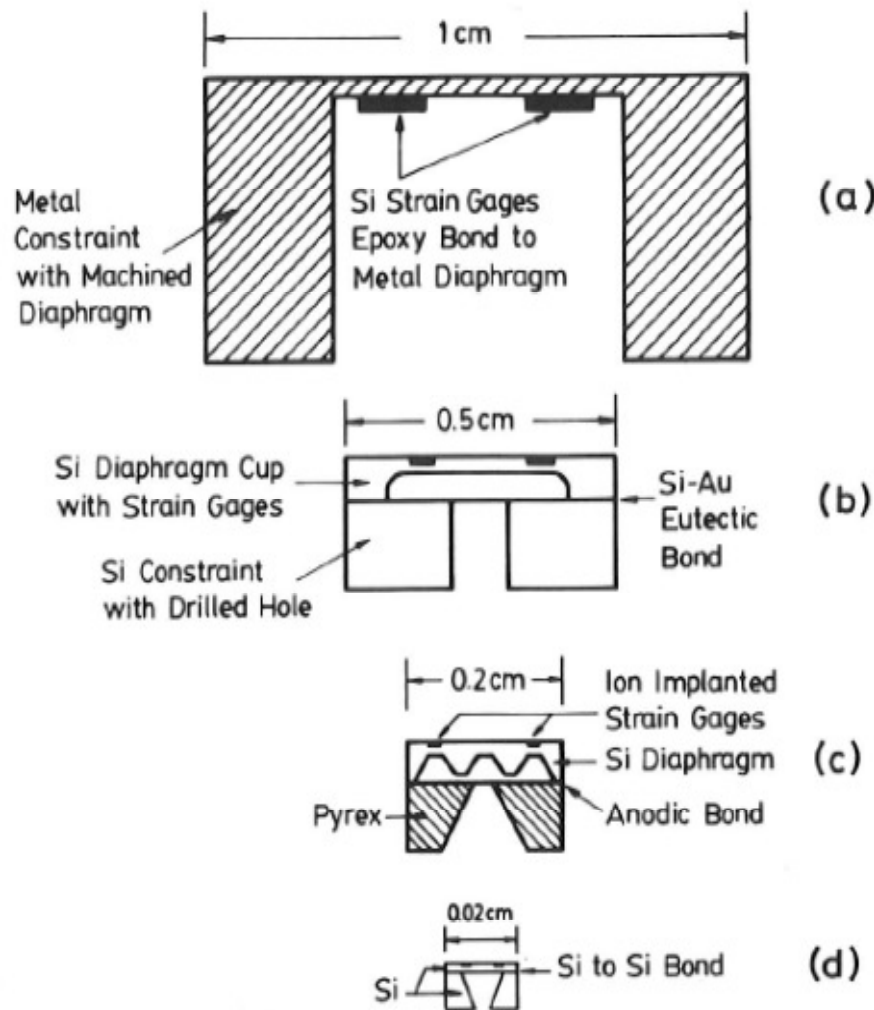
## SENSOR EVOLUTION EXAMPLE

1958 Discovery phase

1965 Basic Technology  
Development phase

1975 Batch process  
phase

1985 Micromachining  
phase

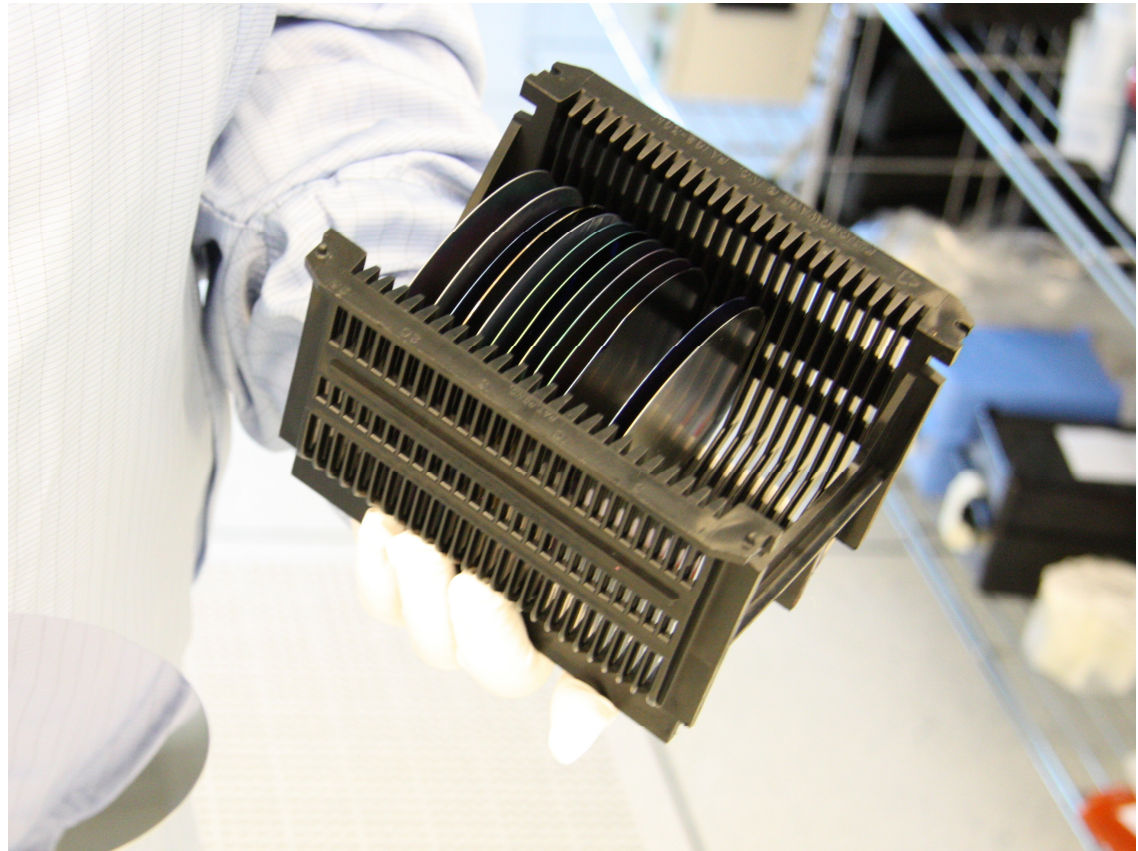


**Fig. 5** Evolution of diaphragm pressure sensors. (After Ref. 11)

- The scope of the course is to give an introduction of **sensors in semiconductor** and **sensors on semiconductor**.
- The most important and best developed processing is by using silicon technology.
- Important is also to understand the most basic conversion techniques and how the sensors are processed/ manufactured.
- Moreover, which type of sensor should be used in a particular situation is of importance

# SEMICONDUCTOR SENSOR TECHNOLOGIES

## CHAPTER 2



# SEMICONDUCTOR SENSOR TECHNOLOGIES

Advantage with silicon processing

- Well developed processing technology, where the microprocessor and memory manufactures have pushed the technology to a sub  $\mu\text{m}$  scale.
- Batch processing result in a large number of sensors fabricated simultaneously at a low cost.

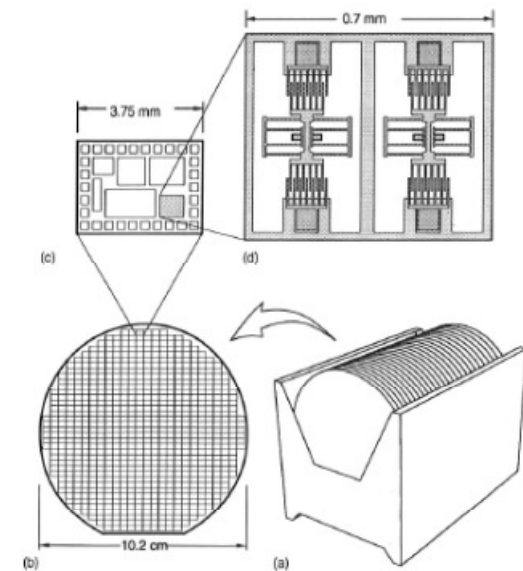


Fig. 2 Batch-fabrication process of microelectronic circuits.

# SEMICONDUCTOR SENSOR TECHNOLOGIES

- Modern Semiconductor technology are based on planar techniques, i.e. 3 dimensional devices are built using stacked layer with different 2 dimensional pattern.
- Surface –micro machined sensor are based on planar techniques
- However, Bulk- micro machined sensor are primarily constructed made by accurate machining of relative thick substrates

# SEMICONDUCTOR SENSOR TECHNOLOGIES

- IMPORTANT PROCESSING STEPS TO FABRICATE A SENSOR ARE
  - Deposition
  - Lithography
  - Etching

# SEMICONDUCTOR SENSOR TECHNOLOGIES

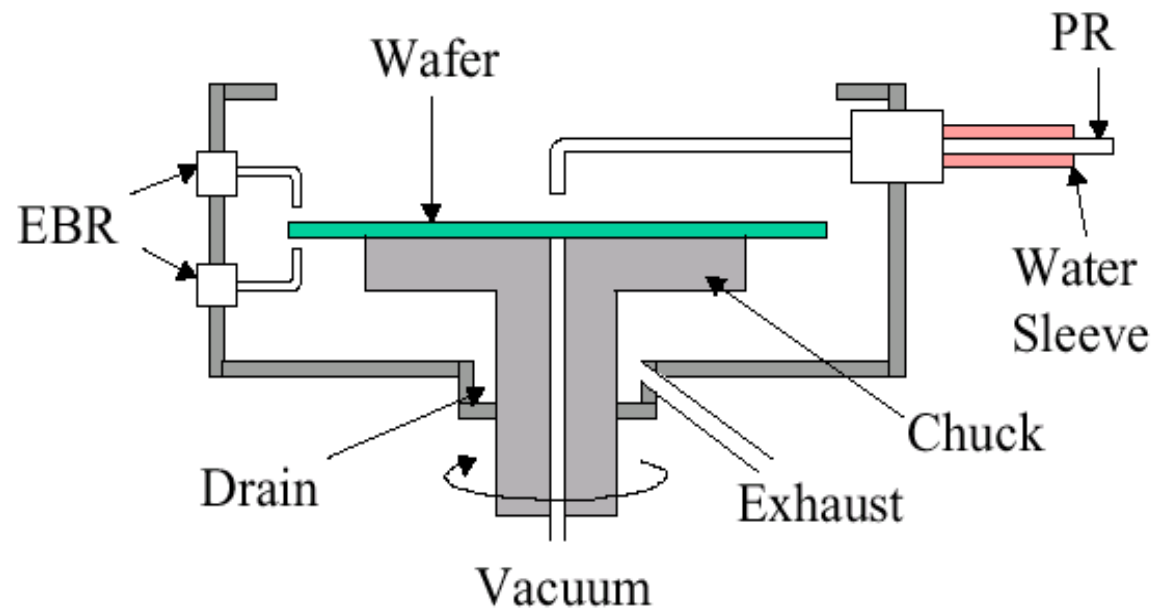
- BASIC FABRICATION STEPS

- Deposition

- Spin Casting
    - Evaporation
    - Sputtering
    - Reactive growth
    - Chemical Vapour deposition
    - Plasma deposition

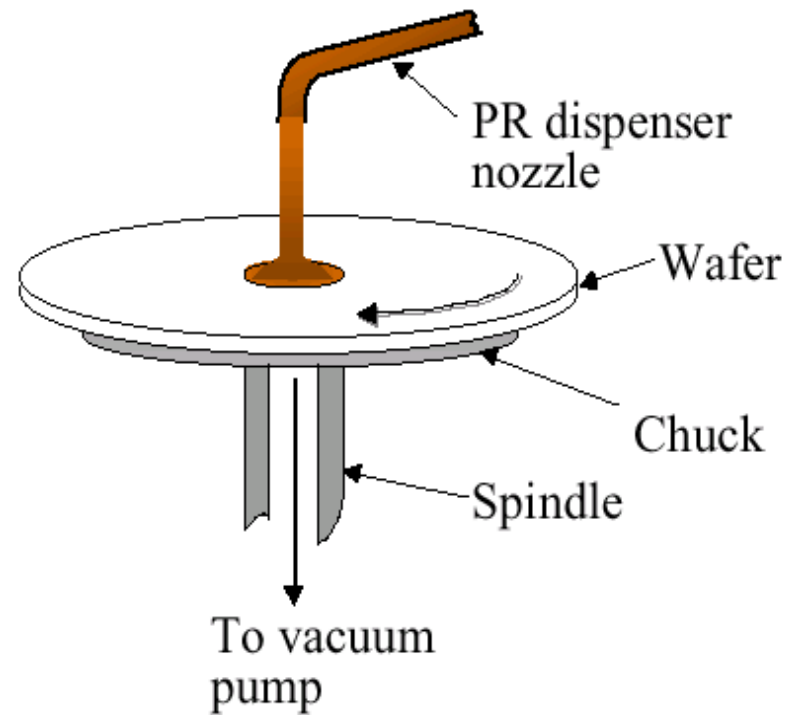
# SPIN CASTING

## Photoresist Spin Coater



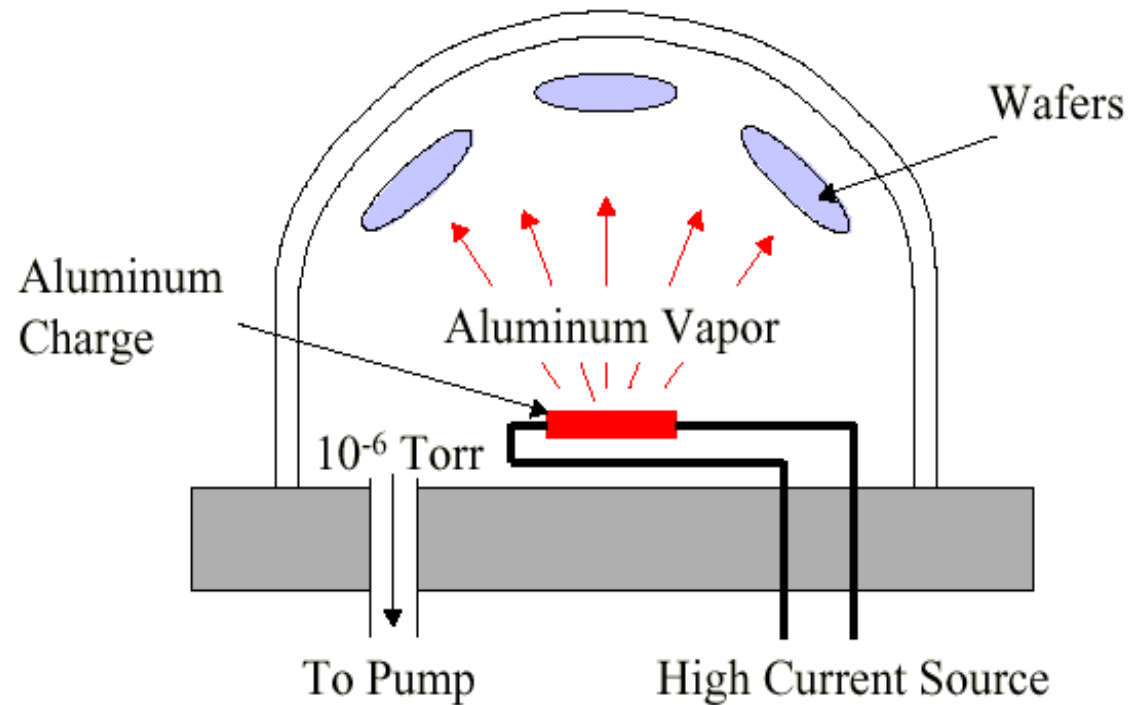
# SPIN CASTING

## Photoresist Applying



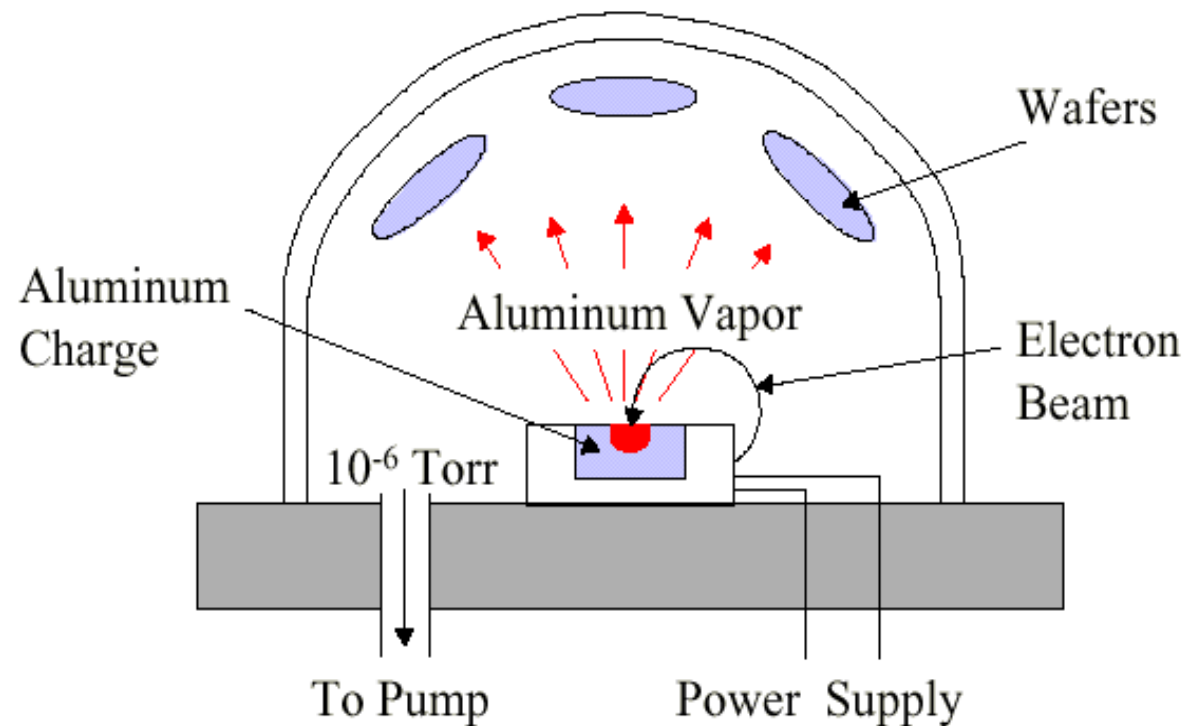
# EVAPORATION

## Thermal Evaporator



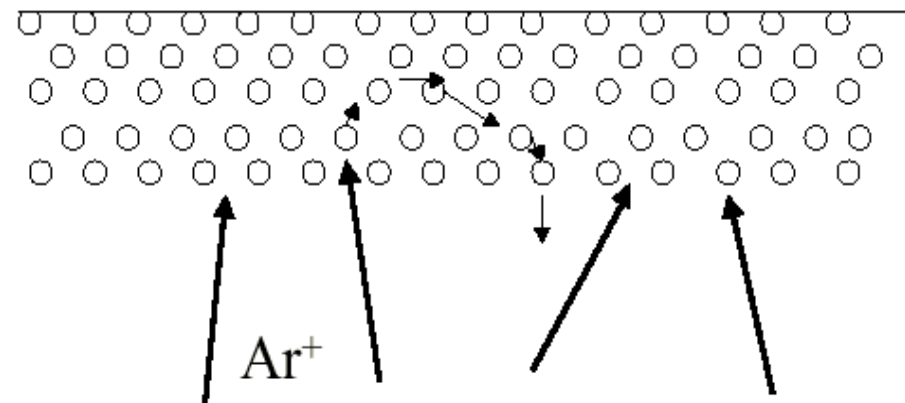
# EVAPORATION

## Electron Beam Evaporator



# SPUTTERING

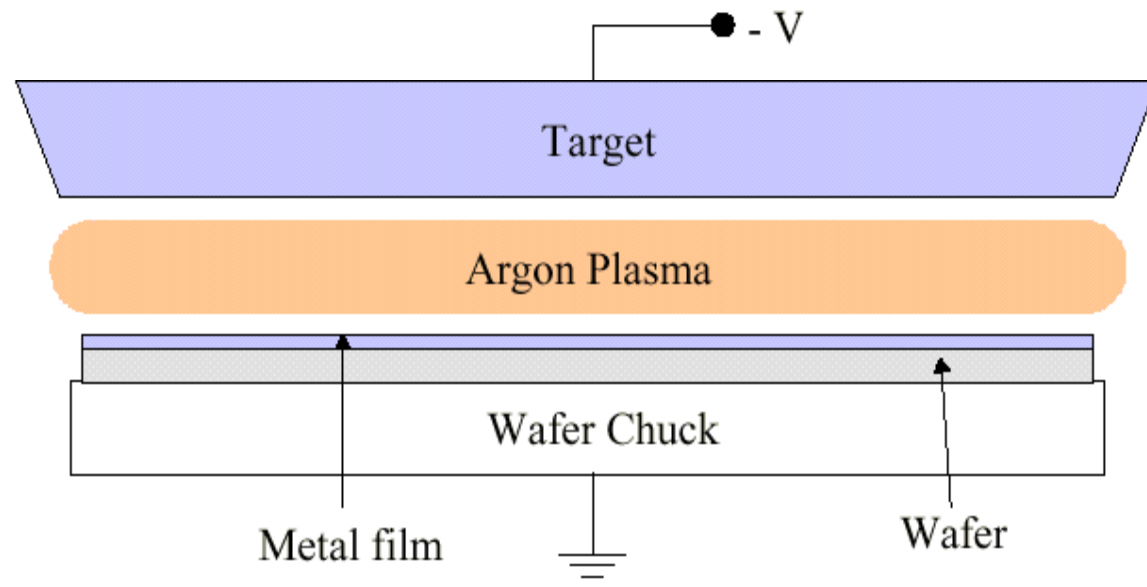
## Sputtering



Momentum transfer will dislodge surface atoms off

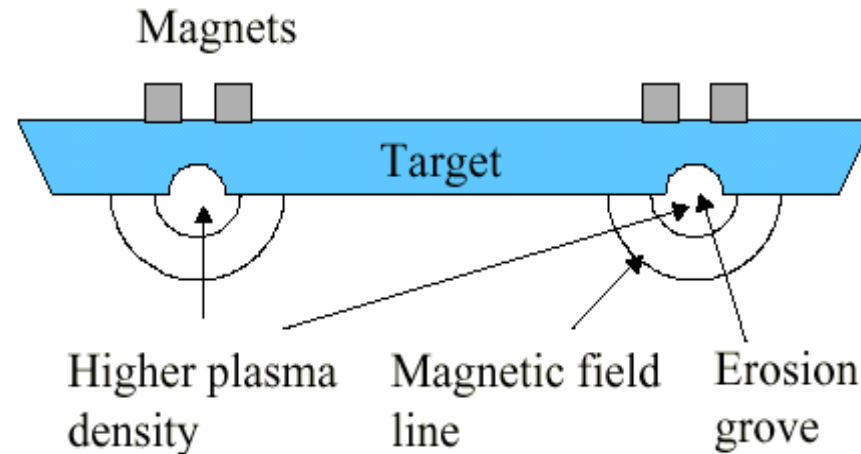
# SPUTTERING

## DC Diode Sputtering



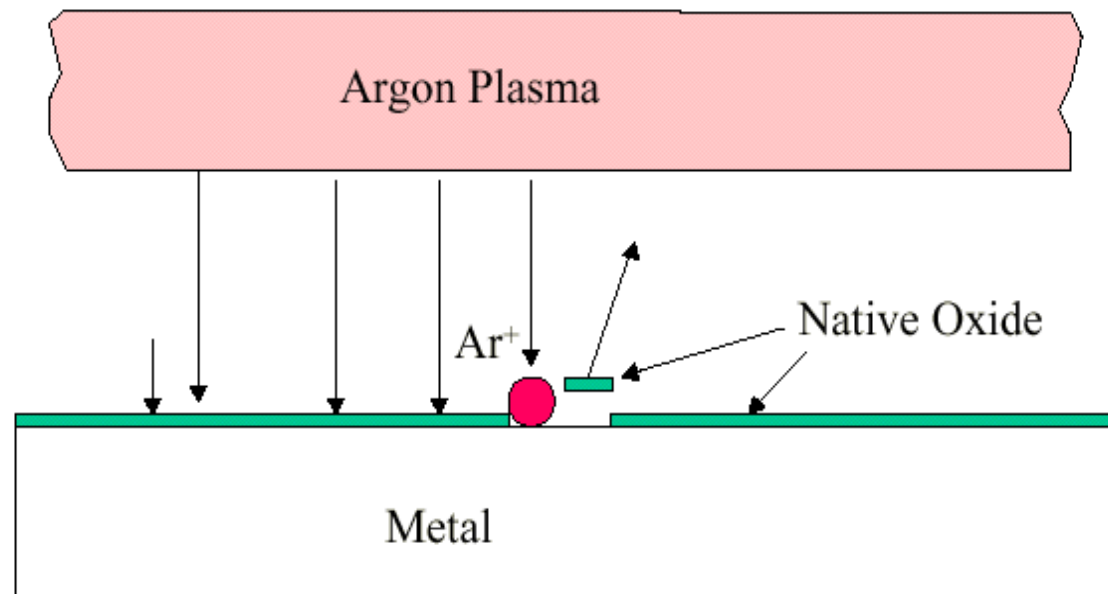
# SPUTTERING

## Schematic of Magnetron Sputtering



# SPUTTERING

## Pre-clean Process



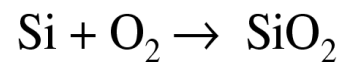
# REACTIVE GROWTH

MATERIAL: SILICON

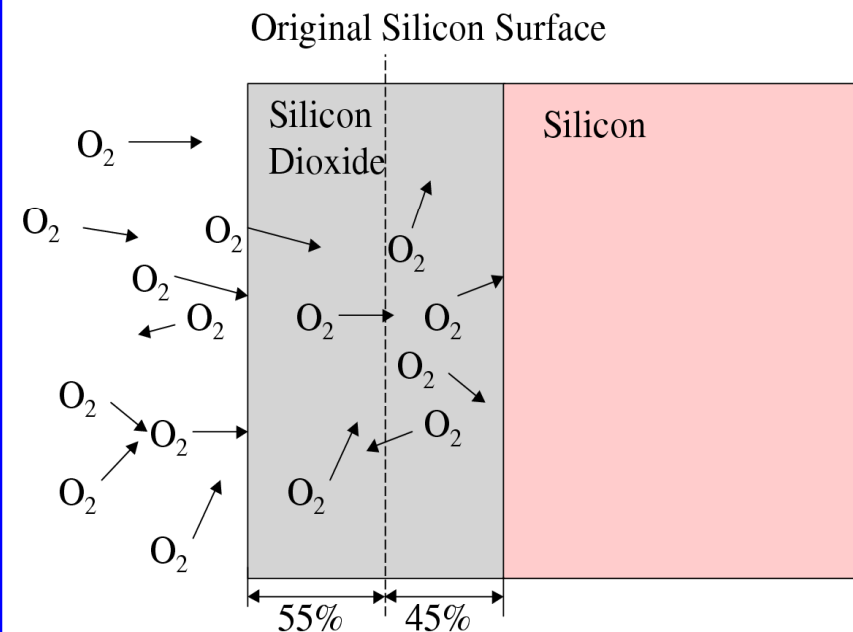
Growth of silicon dioxide,  $\text{SiO}_2$

## Introduction

- Silicon reacts with oxygen
- Stable oxide compound
- Widely used in IC manufacturing



## Oxidation



ong Xiao, Ph. D.

41

# REACTIVE GROWTH

## Application of Oxidation

- Diffusion Masking Layer
- Surface Passivation
  - Screen oxide, pad oxide, barrier oxide
- Isolation
  - Field oxide and LOCOS
- Gate oxide
- Etching mask

## Oxidation Mechanism

- $\text{Si} + \text{O}_2 \longrightarrow \text{SiO}_2$
- Oxygen comes from gas
- Silicon comes from substrate
- Oxygen diffuse cross existing silicon dioxide layer and react with silicon
- The thicker of the film, the lower of the growth rate

# REACTIVE GROWTH

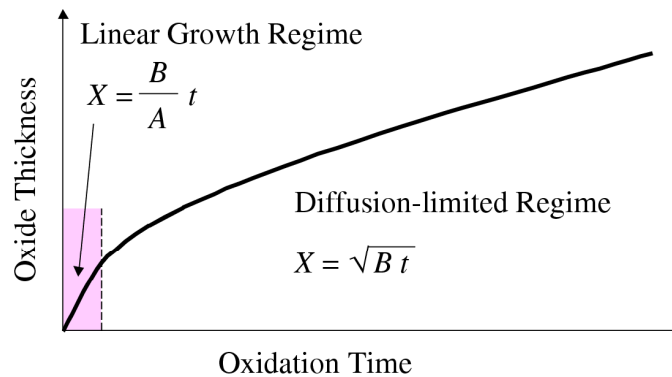
## •OXIDATION

–Dry oxidation “pure O<sub>2</sub>”

–Wet oxidation

•“Water steam” pyrolysis of H<sub>2</sub> in a O<sub>2</sub>-ambient

### Oxide Growth Rate Regime



65

# REACTIVE GROWTH

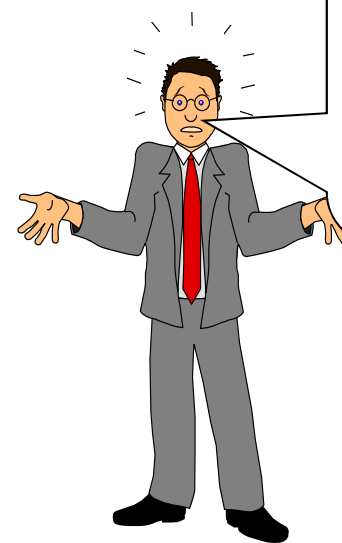
Result of the Deal-Grove model for growth of silicon dioxide

$$\tau = \frac{x_i^2 + Ax_i}{B} \quad x_i \approx 0.02 \mu m (200 \text{\AA})$$

$$X_0 = \frac{A}{2} \left[ \sqrt{1 + \frac{t + \tau}{A^2 / 4B}} - 1 \right]$$

$$B = C_1 e^{-E_1 / kT} \quad \text{parabolic growth}$$

$$\frac{B}{A} = C_2 e^{-E_2 / kT} \quad \text{linear growth}$$



Only valid for  
film thicknesses  
larger than  
200Å !!

# REACTIVE GROWTH

**Table 6-2** Rate constants describing (111) silicon oxidation kinetics at 1 Atm total pressure. For the corresponding values for (100) silicon, all  $C_2$  values should be divided by 1.68.

Ambient	$B$	$B/A$
Dry O <sub>2</sub>	$C_1 = 7.72 \times 10^2 \mu\text{m}^2 \text{hr}^{-1}$ $E_1 = 1.23 \text{ eV}$	$C_2 = 6.23 \times 10^6 \mu\text{m hr}^{-1}$ $E_2 = 2.0 \text{ eV}$
Wet O <sub>2</sub>	$C_1 = 2.14 \times 10^2 \mu\text{m}^2 \text{hr}^{-1}$ $E_1 = 0.71 \text{ eV}$	$C_2 = 8.95 \times 10^7 \mu\text{m hr}^{-1}$ $E_2 = 2.05 \text{ eV}$
H <sub>2</sub> O	$C_1 = 3.86 \times 10^2 \mu\text{m}^2 \text{hr}^{-1}$ $E_1 = 0.78 \text{ eV}$	<del><math>C_2 = 1.63 \times 10^8 \mu\text{m hr}^{-1}</math> <math>E_2 = 2.05 \text{ eV}</math></del>

# REACTIVE GROWTH

## Oxidation Rate

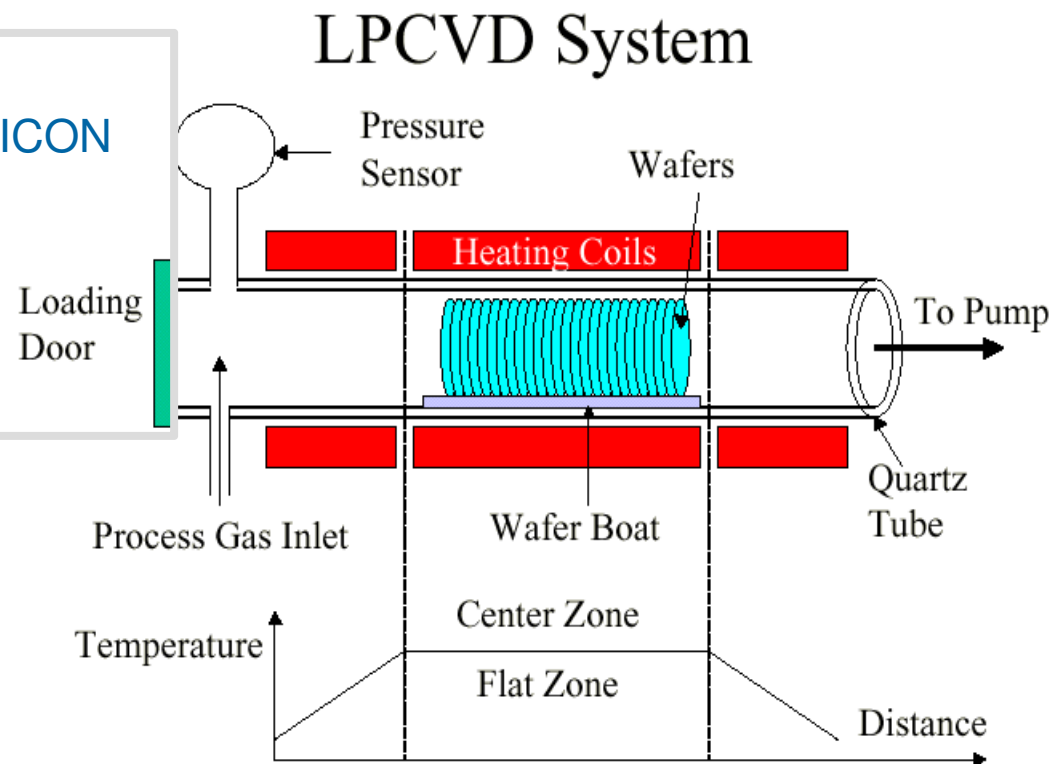
- Temperature
- Chemistry, wet or dry oxidation
- Thickness
- Pressure
- Wafer orientation (<100> vs. <111>)
- Silicon dopant

## Oxidation Rate Wafer Orientation

- <111> surface has higher oxidation rate than <100> surface.
- More silicon atoms on the surface.

# CHEMICAL VAPOUR DEPOSITION (LOW PRESSURE)

- DEPOSITION OF THIN FILM
- TYPICAL DEPOSITION ON SILICON
  - Polycrystalline silicon
  - Silicon dioxide,  $\text{SiO}_2$
  - Silicon nitride,  $\text{Si}_3\text{N}_4$



# CHEMICAL VAPOUR DEPOSITION (LOW PRESSURE)

## LPCVD

- Longer MFP
- Good step coverage & uniformity
- Vertical loading of wafer
- Fewer particles and increased productivity
- Less dependence on gas flow
- Vertical and horizontal furnace

## Dielectric CVD Precursors

- Silane ( $\text{SiH}_4$ )
- TEOS (tetra-ethyl-oxy-silane,  $\text{Si}(\text{OC}_2\text{H}_5)_4$ )

## Sticking Coefficient

- The probability that precursor atom forms chemical bond with surface atom in one collision
- Can be calculated by comparing the calculated deposition rate with 100% sticking coefficient and the measured actual deposition rate

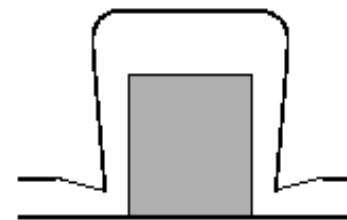
# CHEMICAL VAPOUR DEPOSITION **MIUN.SE** (LOW PRESSURE) DISCOVER YOUR OPPORTUNITIES

## Sticking Coefficient

Precursors	Sticking Coefficient
SiH <sub>4</sub>	$3 \times 10^{-4}$ to $3 \times 10^{-5}$
SiH <sub>3</sub>	0.04 to 0.08
SiH <sub>2</sub>	0.15
SiH	0.94
TEOS	$10^{-3}$
WF <sub>6</sub>	$10^{-4}$

A lower value of sticking coefficient result in a higher surface mobility.

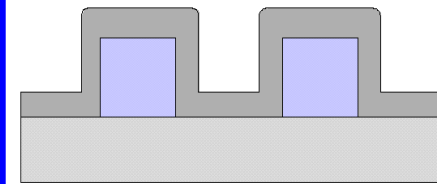
A high value of surface mobility gives a better step covering and a conformal deposition



LPCVD

No mobility

Conformal Deposition Gap Fill

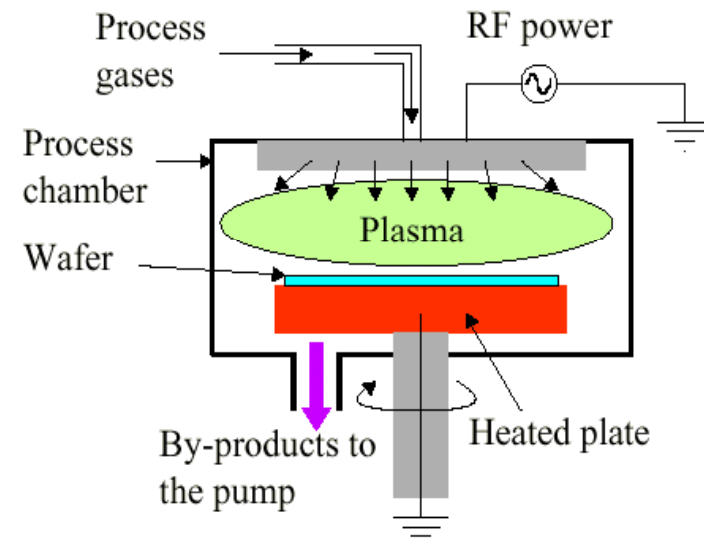


# PLASMA DEPOSITION

## PECVD

- Developed when silicon nitride replaced silicon dioxide for passivation layer.
- High deposition rate at relatively low temp.
- RF induces plasma field in deposition gas
- Stress control by RF
- Chamber plasma clean.

## Plasma Enhanced CVD System



Film contains trapped hydrogen, which alter the etching resistance, properties improves after annealing

# SEMICONDUCTOR SENSOR TECHNOLOGIES

- BASIC FABRICATION STEPS

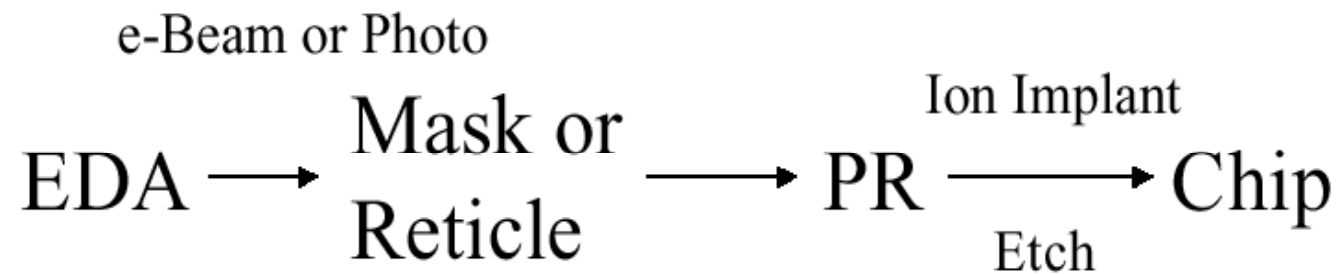
- Lithography

- Mask making
    - Alignment and Exposure
    - Lift-off

- Etching

- Wet chemical etching
    - Dry etching

## IC Fabrication



*Photolithography*

EDA: Electronic Design Automation

PR: Photoresist

# LITHOGRAPHY

## Photoresist

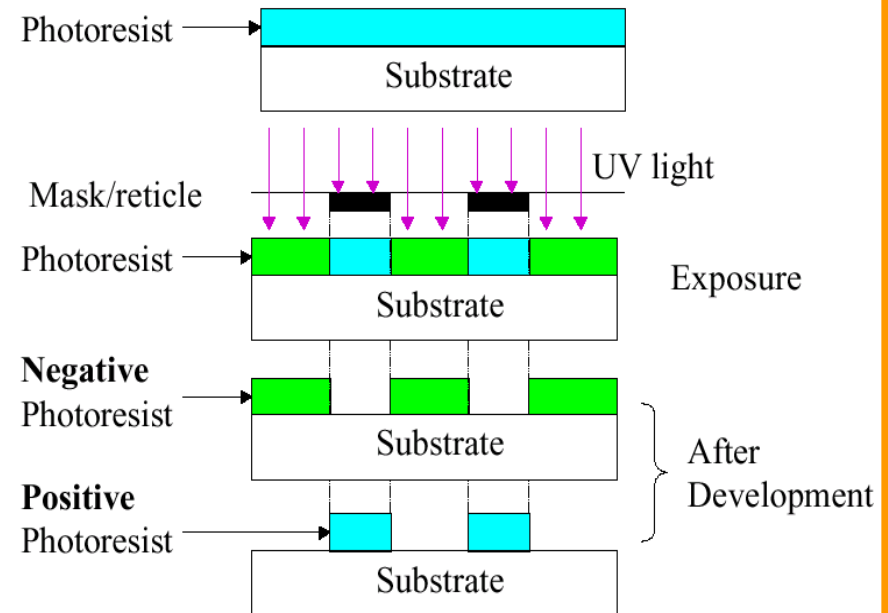
### Negative Photoresist

- Becomes insoluble after exposure
- When developed, the unexposed parts dissolved.
- Cheaper

### Positive Photoresist

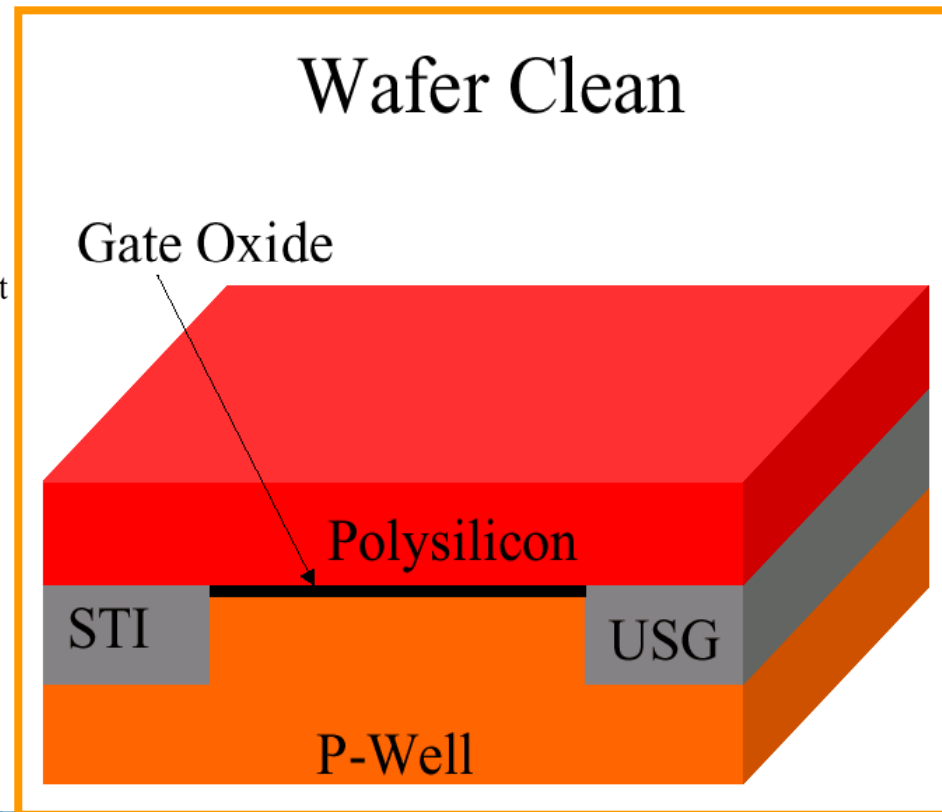
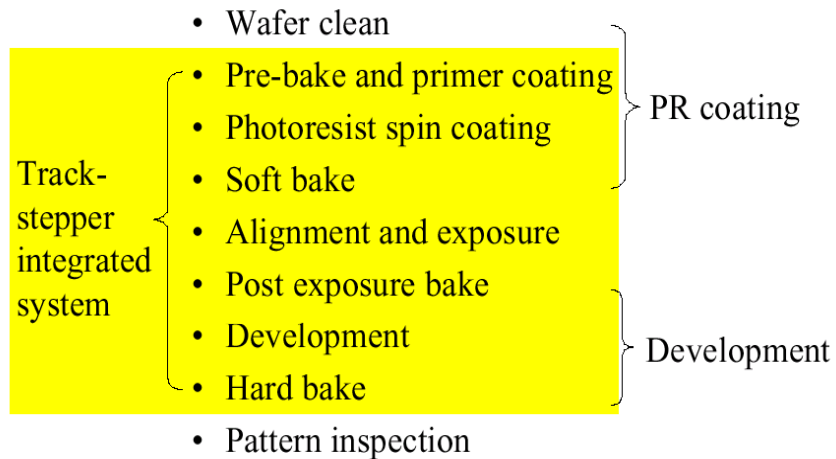
- Becomes soluble after exposure
- When developed, the exposed parts dissolved
- Better resolution

## Negative and Positive Photoresists



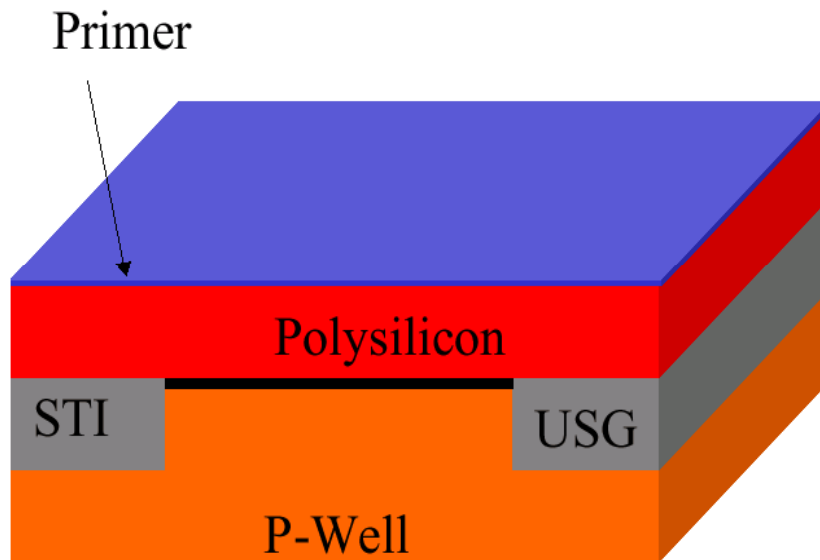
# LITHOGRAPHY

## Basic Steps, Advanced Technology

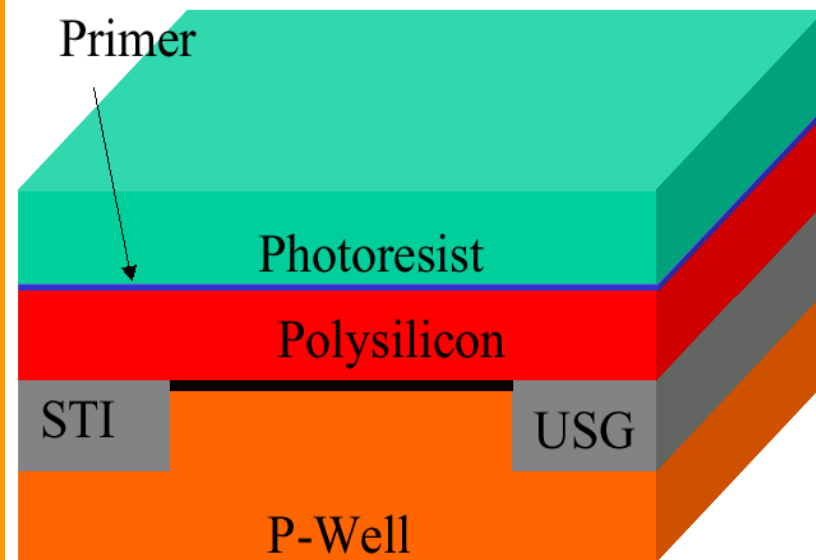


# LITHOGRAPHY

## Pre-bake and Primer Vapor

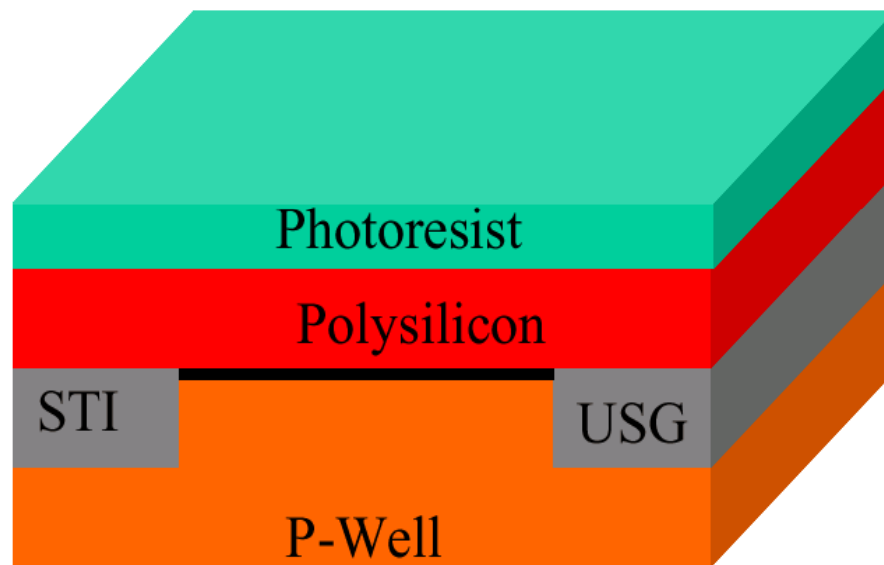


## Photoresist Coating

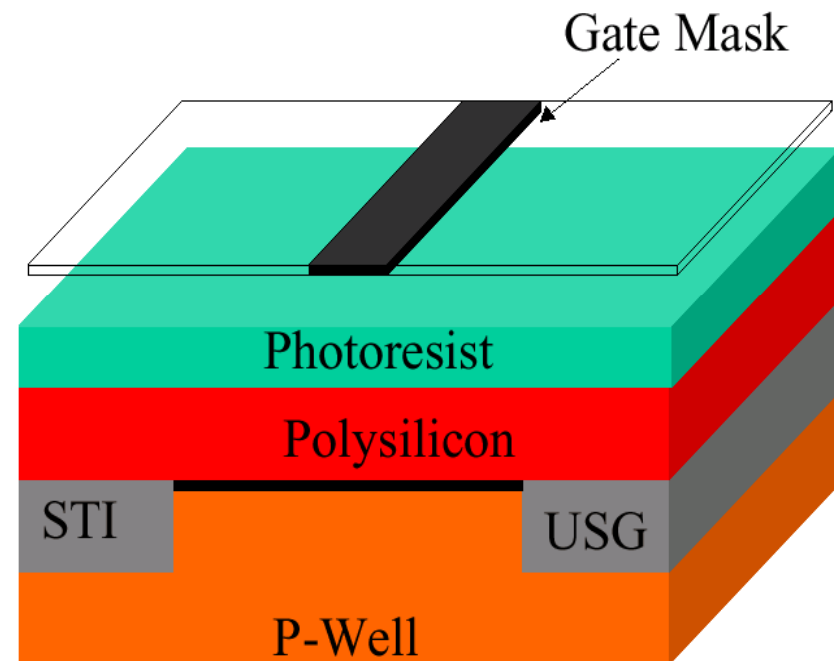


# LITHOGRAPHY

## Soft Bake

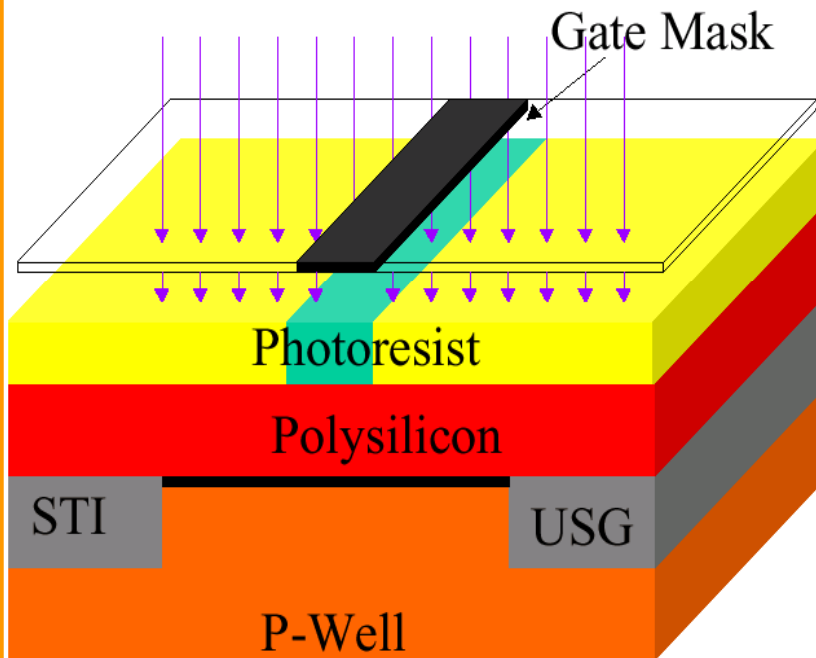


## Alignment and Exposure

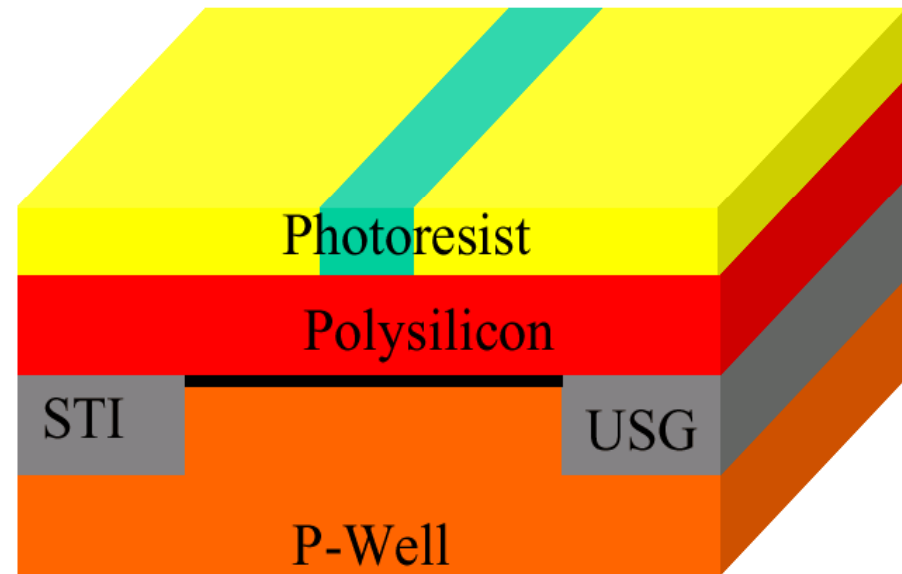


# LITHOGRAPHY

## Alignment and Exposure

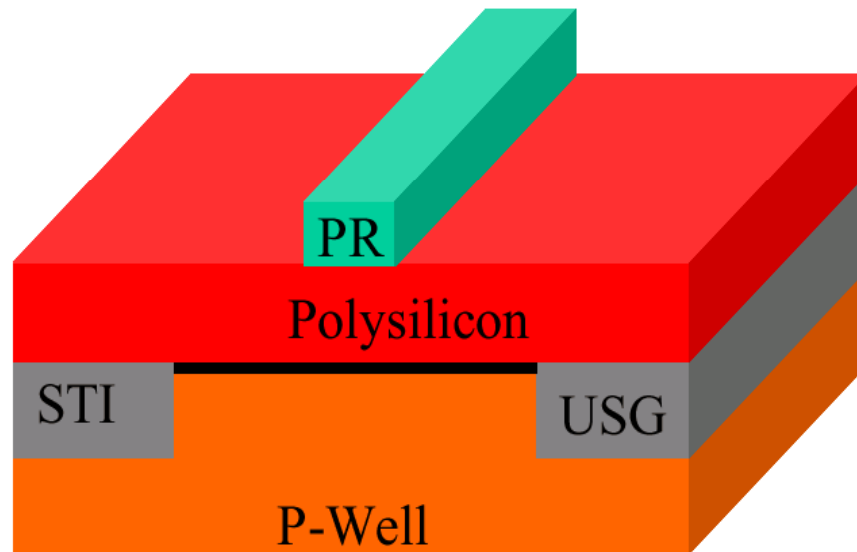


## Post Exposure Bake

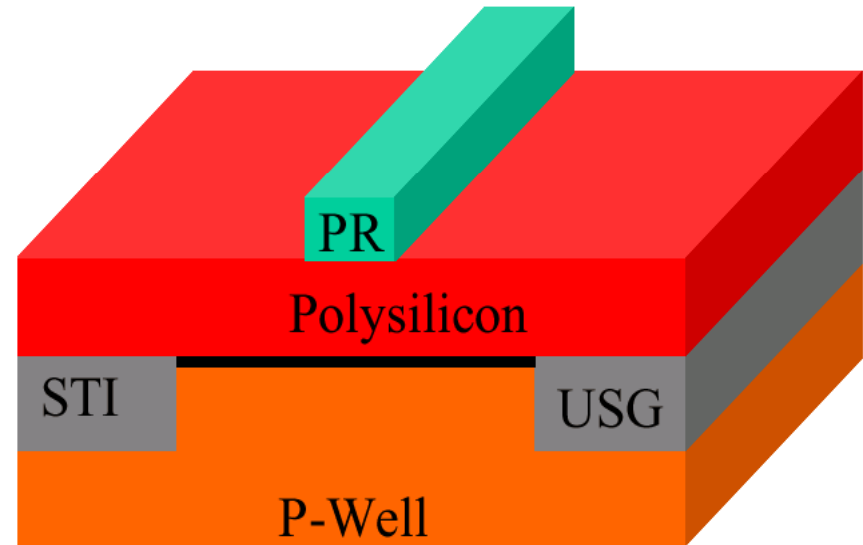


# LITHOGRAPHY

## Development

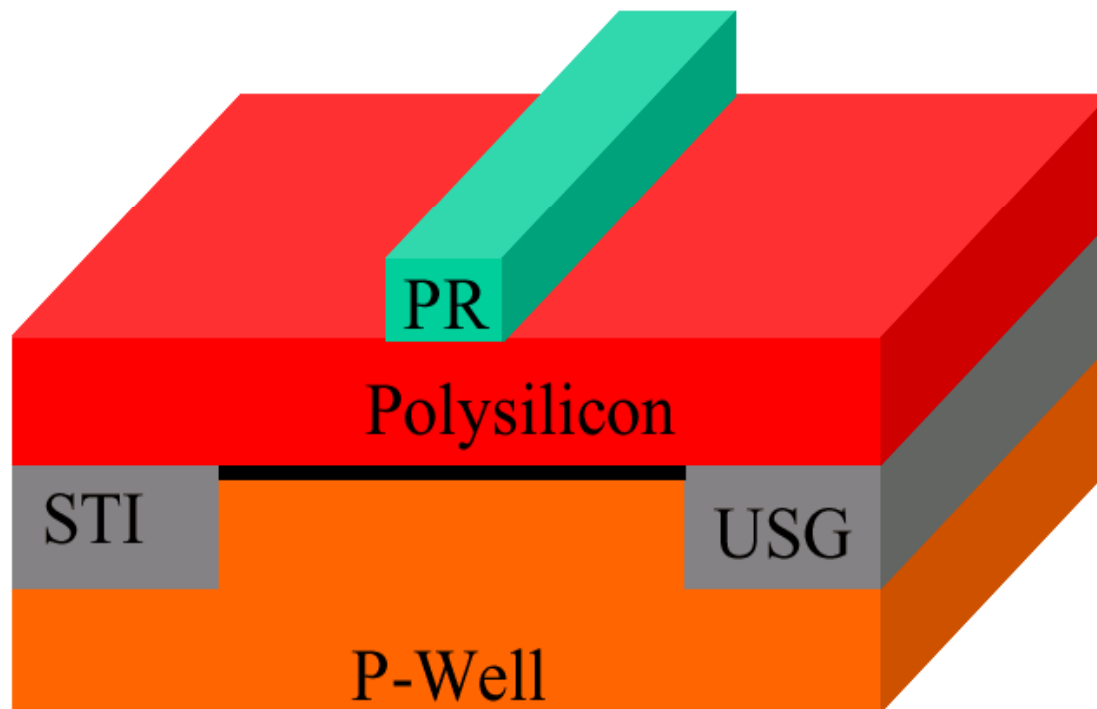


## Hard Bake



# LITHOGRAPHY

## Pattern Inspection

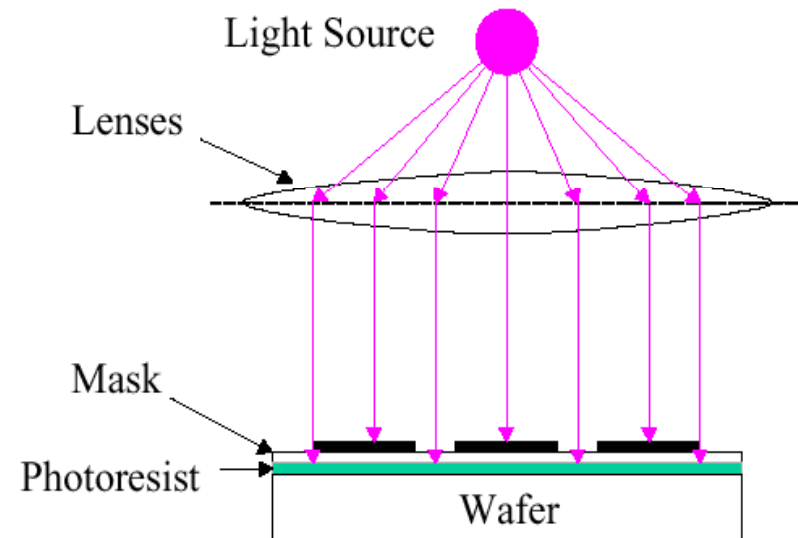


# LITHOGRAPHY

## Alignment and Exposure Tools

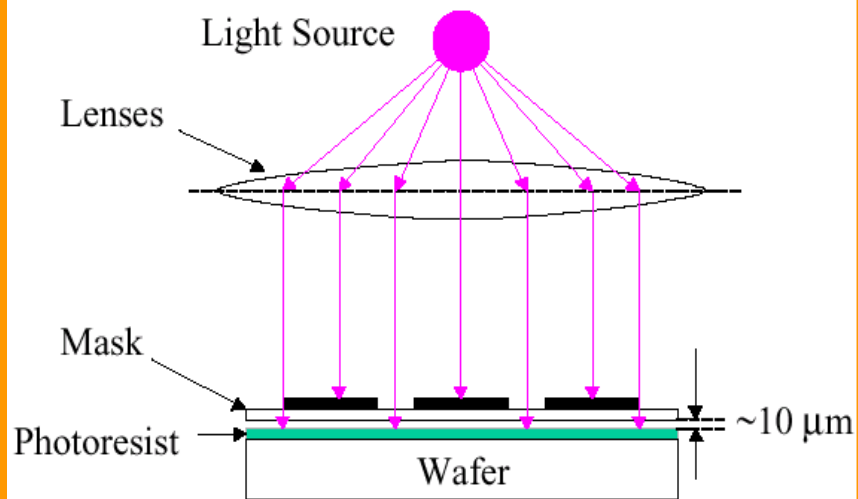
- Contact printer
- Proximity printer
- Projection printer
- Stepper

## Contact Printer

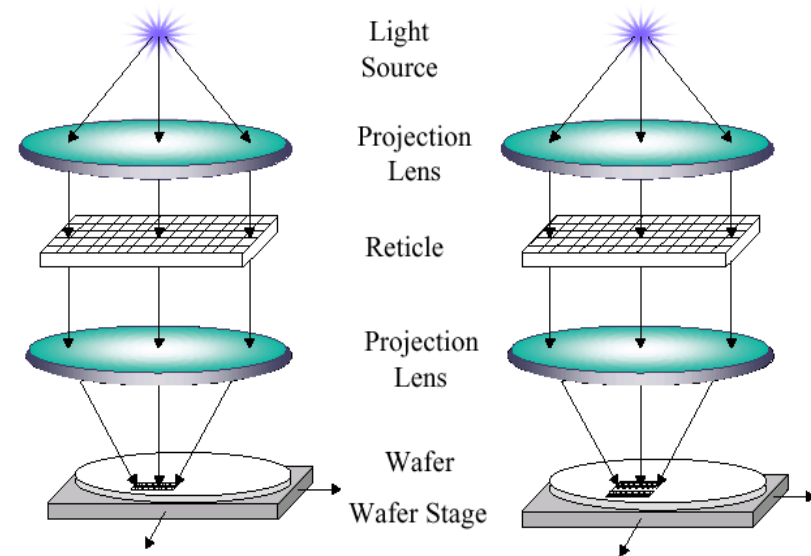


# LITHOGRAPHY

## Proximity Printer



## Step-&-Repeat Alignment/Exposure



# LITHOGRAPHY

## Photolithography Light Sources

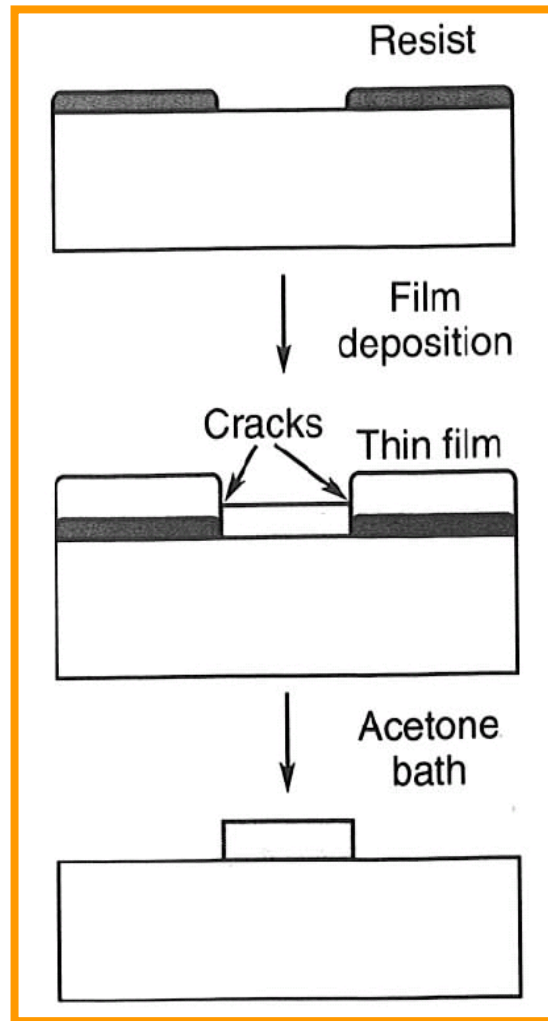
	Name	Wavelength (nm)	Application feature size ( $\mu\text{m}$ )
Mercury Lamp	G-line	436	0.50
	H-line	405	
	I-line	365	0.35 to 0.25
Excimer Laser	XeF	351	
	XeCl	308	
	KrF (DUV)	248	0.25 to 0.15
	ArF	193	0.18 to 0.13
Fluorine Laser	F <sub>2</sub>	157	0.13 to 0.1

- Smaller objects need shorter wavelength

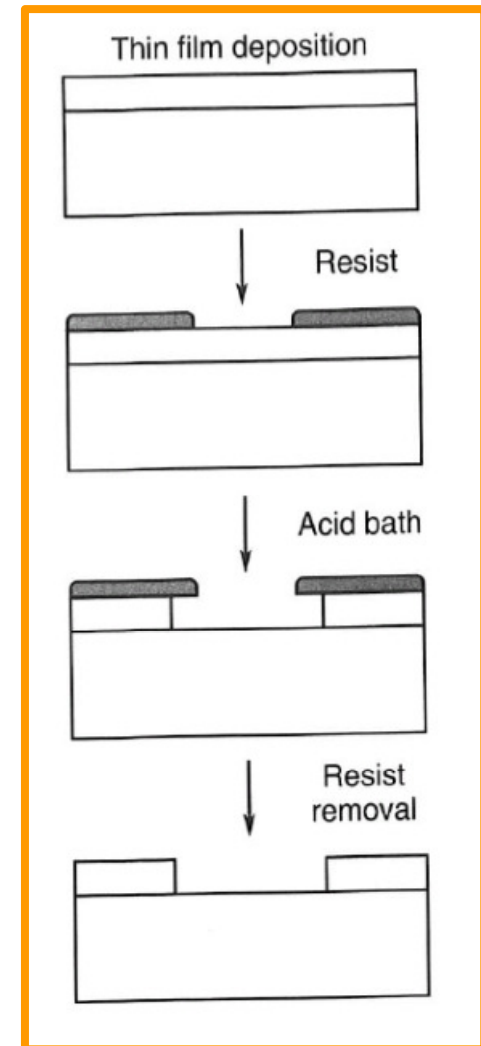
- But this results in a worse depth of focus, therefore there is a requirement for surface planarization

# LITHOGRAPHY

## •Lift-off



## •Etching



# ETCHING

## Etch Rate

Etch rate measures of the how fast the material is removed from wafer surface.

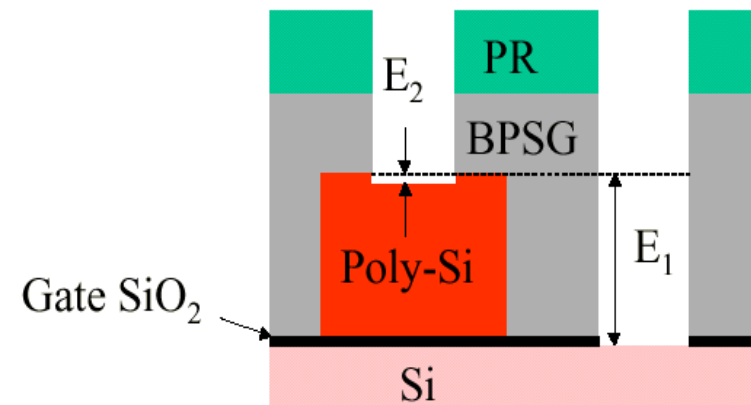


$$\text{Etch Rate} = \frac{\Delta d}{t} \text{ (Å/min)}$$

$\Delta d = d_0 - d_1$  (Å) is thickness change and  $t$  is etch time (min)

## Selectivity

- Selectivity of BPSG to Poly-Si:  $S = \frac{E_1}{E_2}$

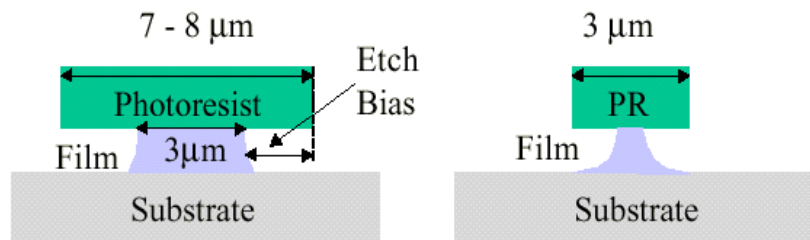


Boron Phosphorus silicate glass  
BPSG

# ETCHING

## WET ETCHING

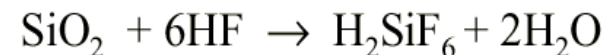
### Wet Etch Profiles



- Can't be used for feature size is smaller than 3 μm
- Replaced by plasma etch for all patterned etch

### Wet Etching Silicon Dioxide

- Hydrofluoric Acid (HF) Solution
- Normally diluted in buffer solution or DI water to reduce etch rate.



- Widely used for CVD film quality control
- BOE: Buffered oxide etch
- WERR: wet etch rate ratio

# ETCHING

## DRY ETCHING (PLASMA)

### Chemical Etch

- Purely chemical reaction
- By products are gases or soluble in etchants
- High selectivity
- Isotropic etch profile
- Examples:
  - Wet etch
  - Dry strip

### Physical Etch

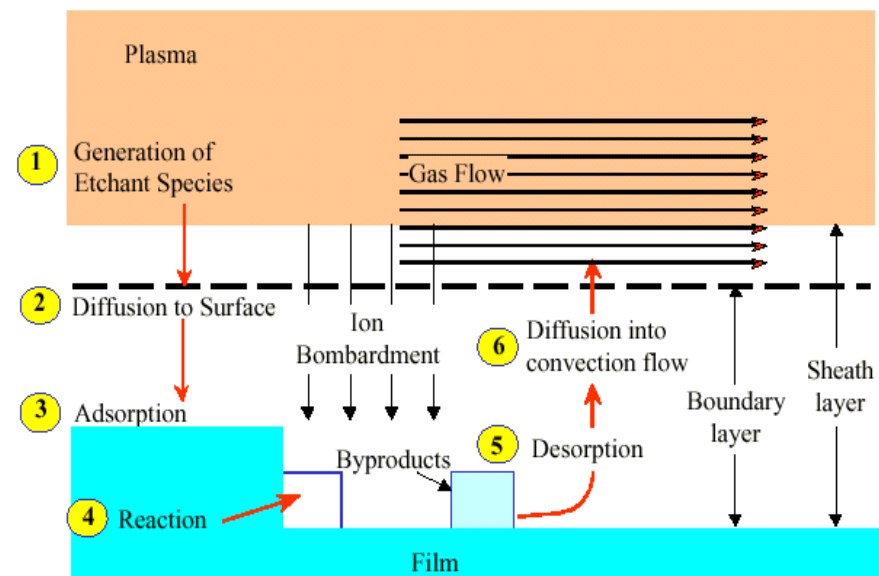
- Bombardment with inert ions such as  $\text{Ar}^+$
- Physically dislodging material from surface
- Plasma process
- Anisotropic profile
- Low selectivity
- Example:
  - Argon sputtering etch

# ETCHING

## Reactive Ion Etch (RIE)

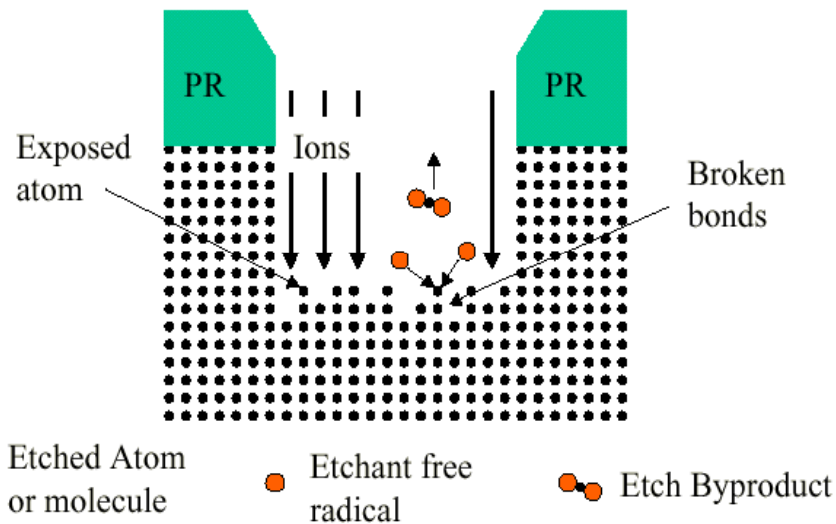
- Combination of chemical and physical etch
- Plasma process, ion bombardment plus free radicals
- Misleading name, should be called ion assistant etch (IAE)
- High and controllable etch rate
- Anisotropic and controllable etch profile
- Good and controllable selectivity
- All patterned etches are RIE processes in 8" fabs

## Etch Process Sequence

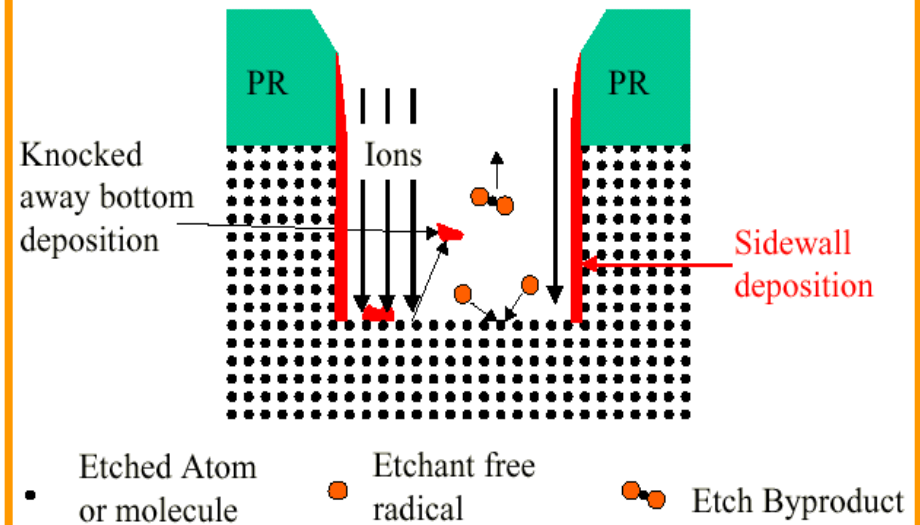


# ETCHING

## Damage Mechanism



## Blocking Mechanism

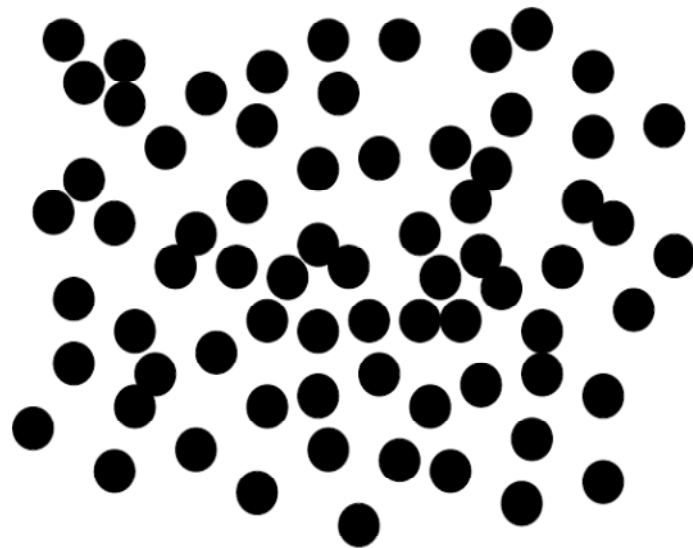


# SEMICONDUCTOR SENSOR TECHNOLOGIES

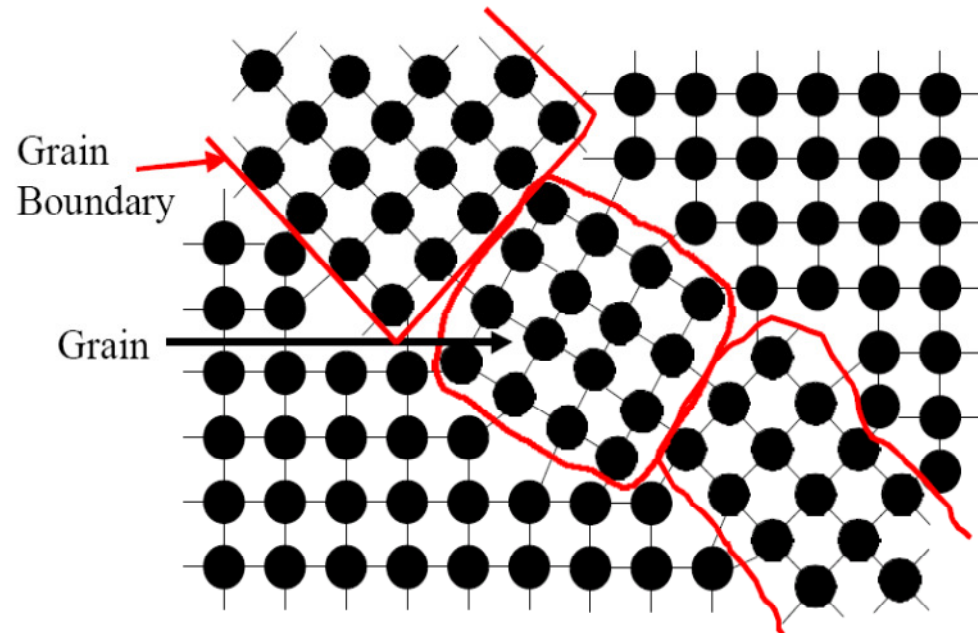
- BULK MICROMACHINING
  - Bulk materials
  - Anisotropic silicon etching
  - Wafer bonding
- SURFACE MICROMACHINING
  - Thin film Materials
  - Thin film etching
  - Sacrificial etching

# BULK MATERIALS

## Amorphous Structure

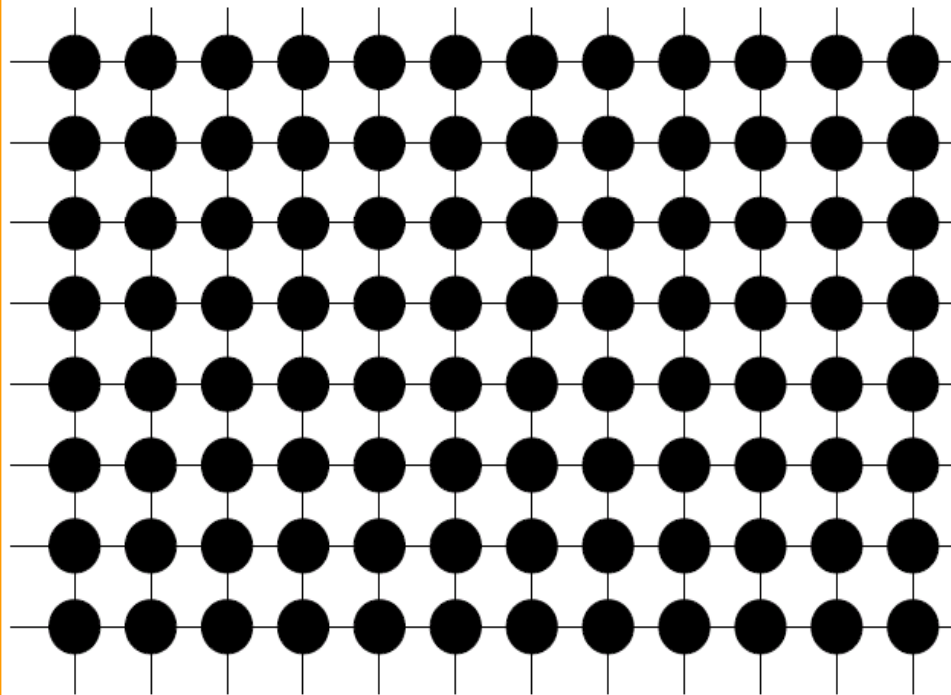


## Polycrystalline Structure



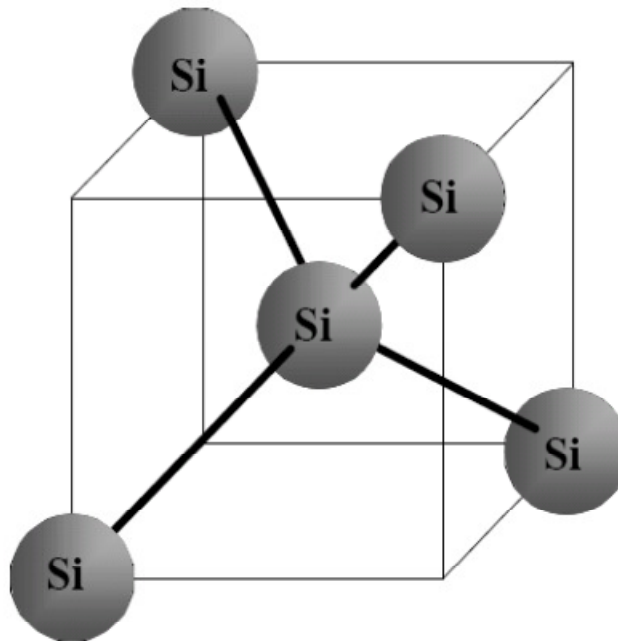
# BULK MATERIALS

## Single Crystal Structure



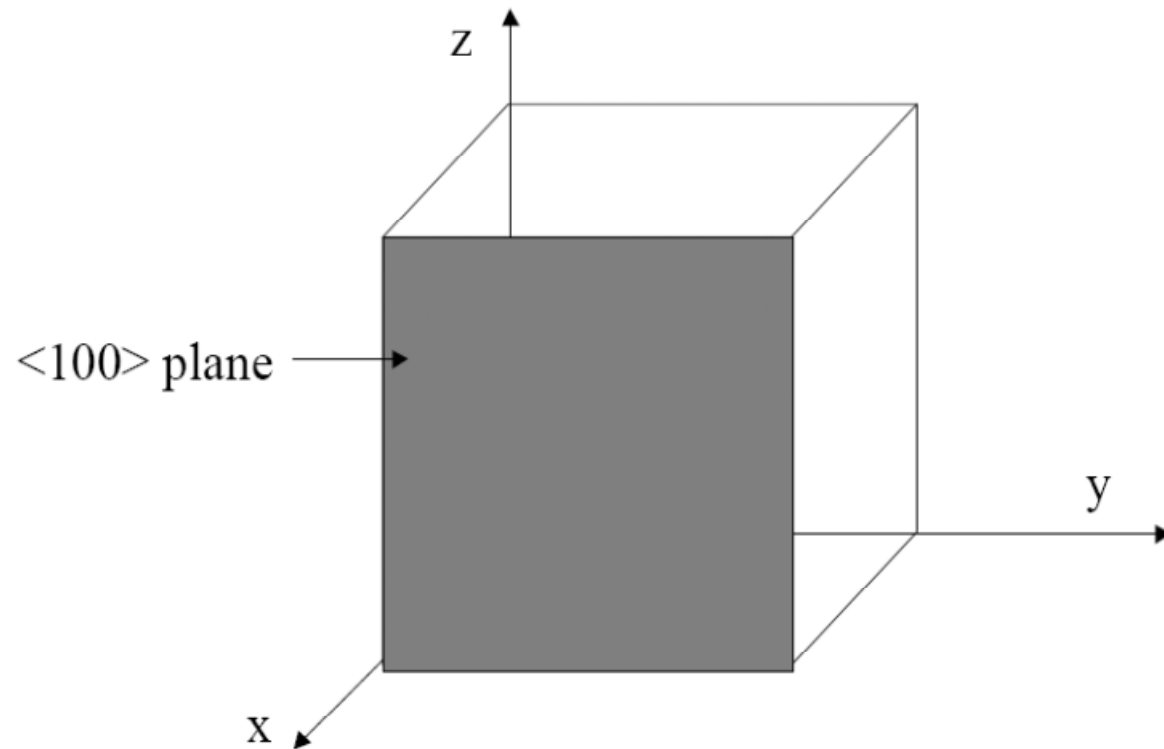
# BULK MATERIALS

## Unit Cell of Single Crystal Silicon

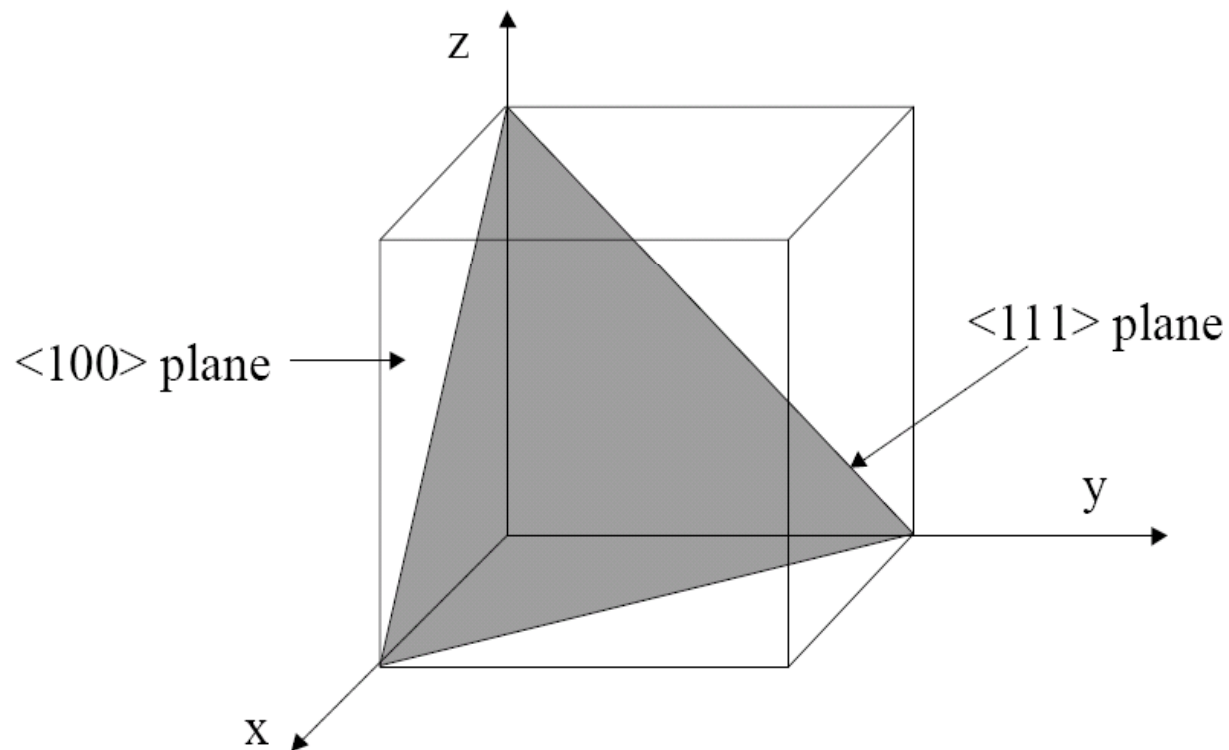


# BULK MATERIALS

Crystal Orientations:  $\langle 100 \rangle$

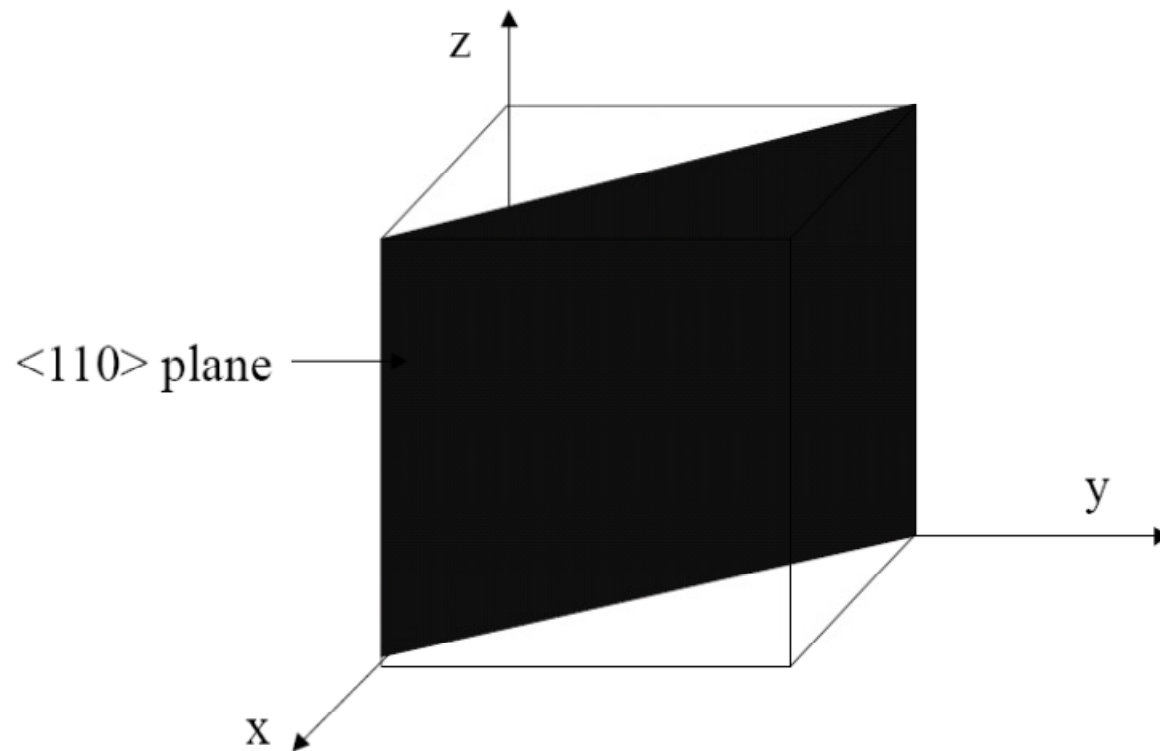


## Crystal Orientations: $\langle 111 \rangle$



# BULK MATERIALS

Crystal Orientations:  $\langle 110 \rangle$

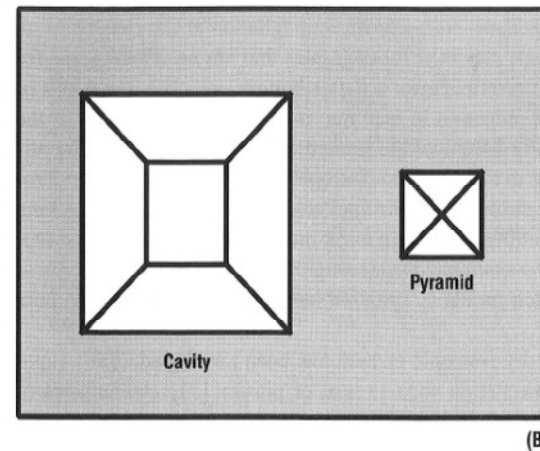
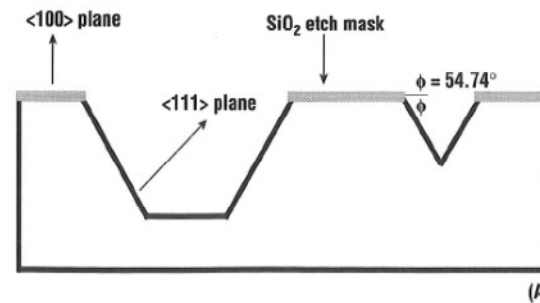


# ANISOTROPIC SILICON ETCHING

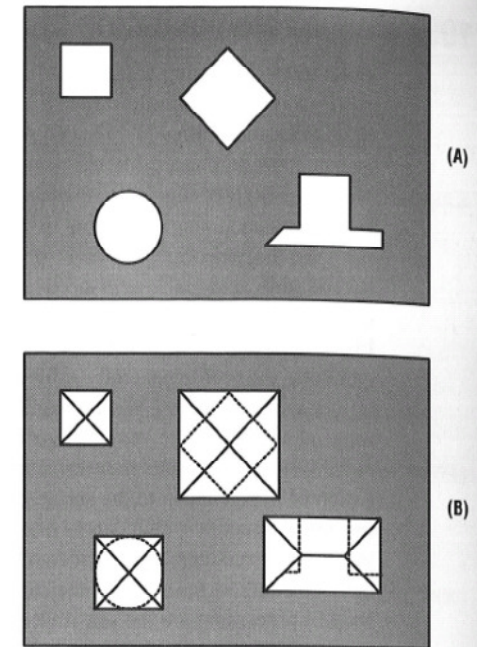
Etching speed

$(110) > (100) > (111)$

Selectivity  $S = \frac{(100)}{(111)}$

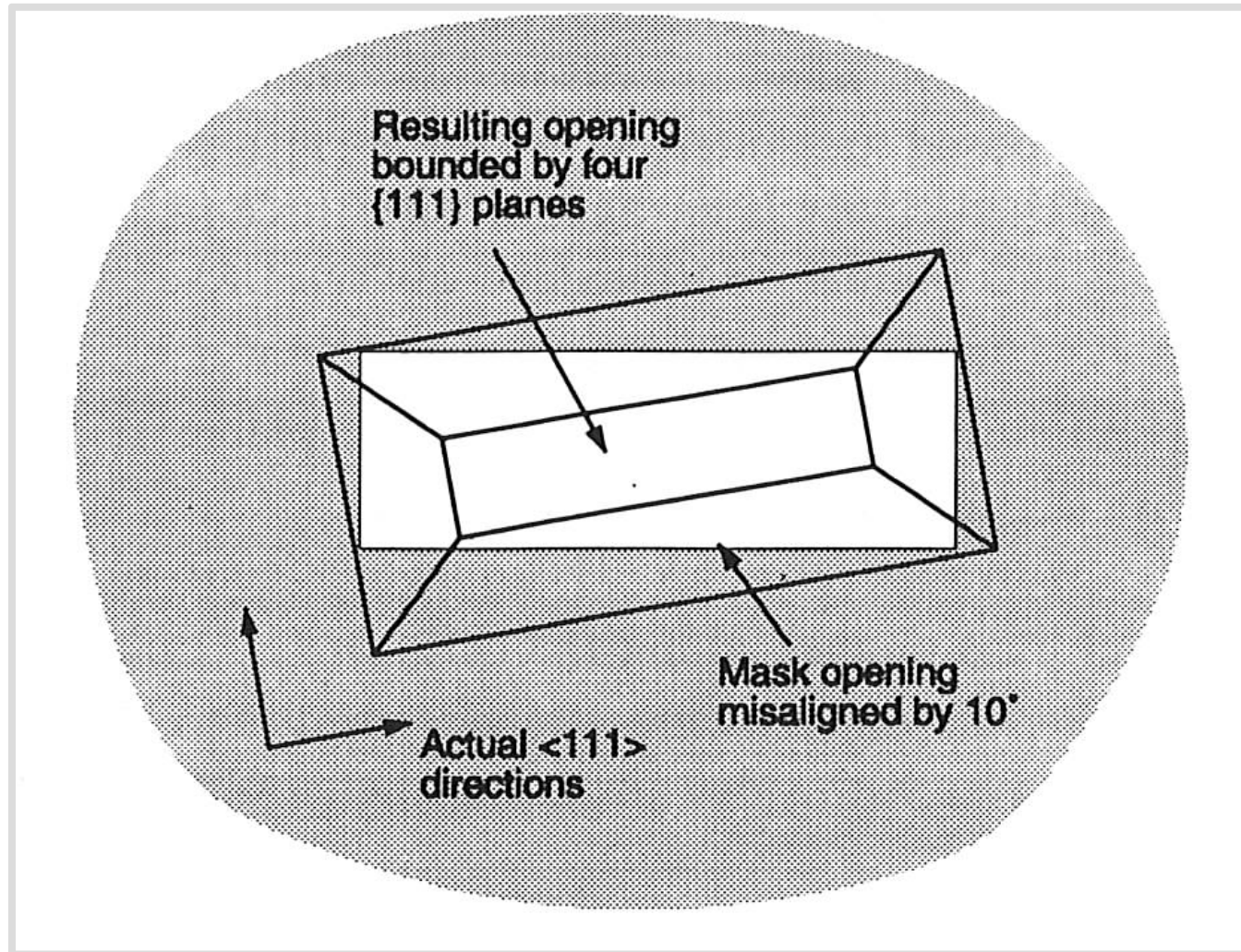


**Figure 19.10** Cross section (A) and top view (B) of pyramidal holes and cavities formed in a (100) silicon wafer with an anisotropic etchant.



**Figure 19.11** Effect of mask opening orientation on the etch profile. (A) Top view of mask openings as oriented to the <110> direction. (B) Etched structures resulting for an anisotropic etchant on (100) silicon.

# ANISOTROPIC SILICON ETCHING



# ANISOTROPIC SILICON ETCHING

## Example 19.4

Find the size of the mask opening that after anisotropic etching will yield a flat rectangular area of size  $100\text{ }\mu\text{m}$  by  $200\text{ }\mu\text{m}$ ,  $80\text{ }\mu\text{m}$  below the silicon (100) surface.

From the side view we find the length  $X$  to be

$$X = 100\text{ }\mu\text{m} + 2Z$$

where  $Z$  is defined by the relation

$$\tan \phi = \tan 54.74^\circ = \frac{80\text{ }\mu\text{m}}{Z} = 1.41$$

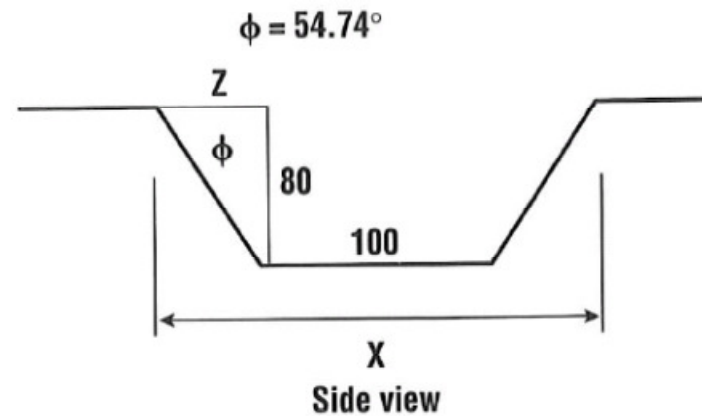
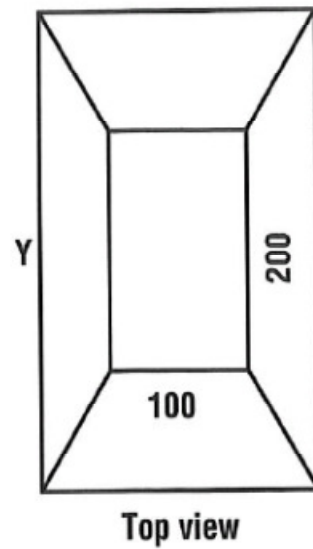
Solving for  $X$  gives

$$X = 100\text{ }\mu\text{m} + 2 \frac{80\text{ }\mu\text{m}}{\tan 54.74^\circ} = 213.2\text{ }\mu\text{m}$$

# ANISOTROPIC SILICON ETCHING

Similarly, solving for  $Y$  yields

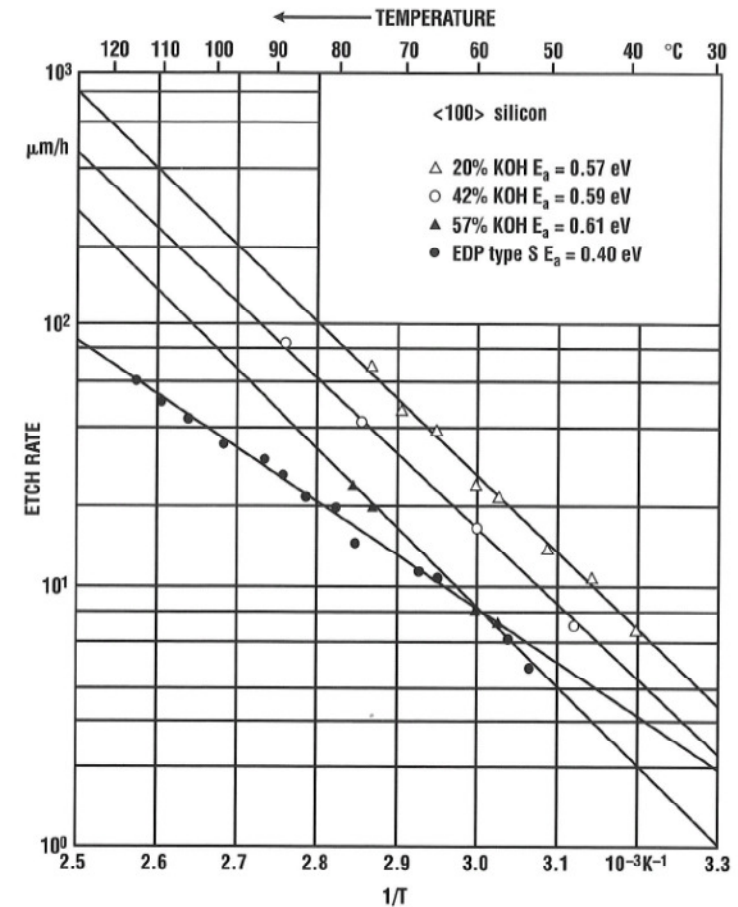
$$Y = 200 \mu\text{m} + 2 \frac{80 \mu\text{m}}{\tan 54.74^\circ} = 313.2 \mu\text{m}$$



# ANISOTROPIC SILICON ETCHING

Controlling of etch depth by;

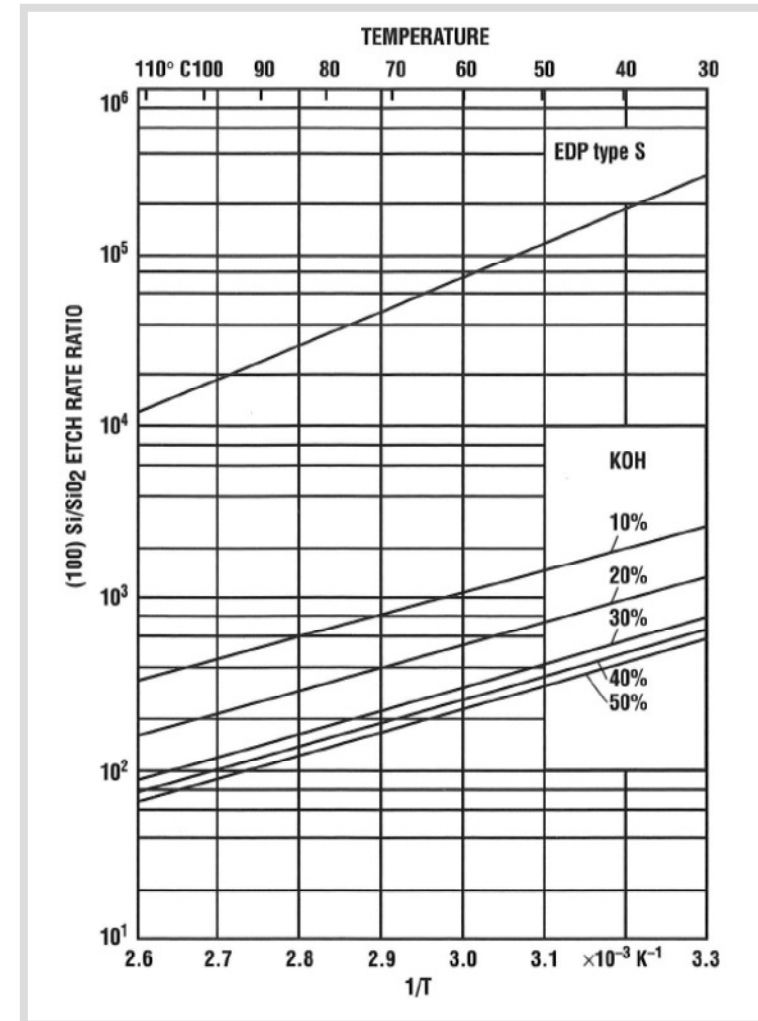
1. Timed etches
2. Anisotropic etching of v grooves
3.  $P^{++}$  doping
4. Electrochemical etch stop.



**Figure 19.13** Arrhenius plot of the vertical etching rate for (100) silicon wafers for EDP and KOH solutions (after Seidel [33], reproduced by permission of The Electrochemical Society, Inc.).

# ANISOTROPIC SILICON ETCHING

Selectivity  $\text{SiO}_2$ -Si(100)



# ANISOTROPIC SILICON ETCHING

**Table 19.2** Principal characteristics of four different common anisotropic etchants<sup>a</sup>

Etchant/Diluent/ Additives/ Temperature	Etch Stop	Etch Rate (100) (mm/min)	Etch Rate Ratio (100)/(111)	Remarks	Mask (Etch Rate)
KOH/water, isopropyl alcohol additive, 85°C	$Is > 10^{20} \text{ cm}^{-3}$ reduces etch rate by 20	1.4	400 and 600 for (110)/ (111)	IC incompatible, avoid eye contact, etches oxide fast, lots of $\text{H}_2$ bubbles	Photoresist (shallow etch at room temperature); $\text{Si}_3\text{N}_4$ (not attacked); $\text{SiO}_2$ (28 Å/min)
Ethylene diamine pyrocatechol (water), pyrazine additive, 115°C	$\geq 5 \times 10^{10} \text{ cm}^{-3}$ reduces the etch rate by 50	1.25	35	Toxic, ages fast, $\text{O}_2$ must be excluded few $\text{H}_2$ bubbles, silicates may precipitate	$\text{SiO}_2$ (2–5 Å/min); $\text{Si}_3\text{N}_4$ (1 Å/min); Ta, Au, Cr, Ag, Cu
Tetramethyl ammonium (TMAH) (water), 90°C	$> 4 \times 10^{20} \text{ cm}^{-3}$ reduces etch rate by 40	1	From 12.5 to 50	IC compatible, easy to handle, smooth surface finish, few studies	$\text{SiO}_2$ etch rate is 4 orders of magnitude lower than (100) Si LPCVD $\text{Si}_3\text{N}_4$
$\text{N}_2\text{H}_4$ /(water), isopropyl alcohol, 115°C	$> 1.5 \times 10^{20} \text{ cm}^{-3}$ practically stops the etch	3.0	10	Toxic and explosive, okay at 50% water	$\text{SiO}_2$ (<2 Å/min) and most metallic films; does not attack Al according to some authors

<sup>a</sup> Given the many possible variables, the data in the table are only typical examples.

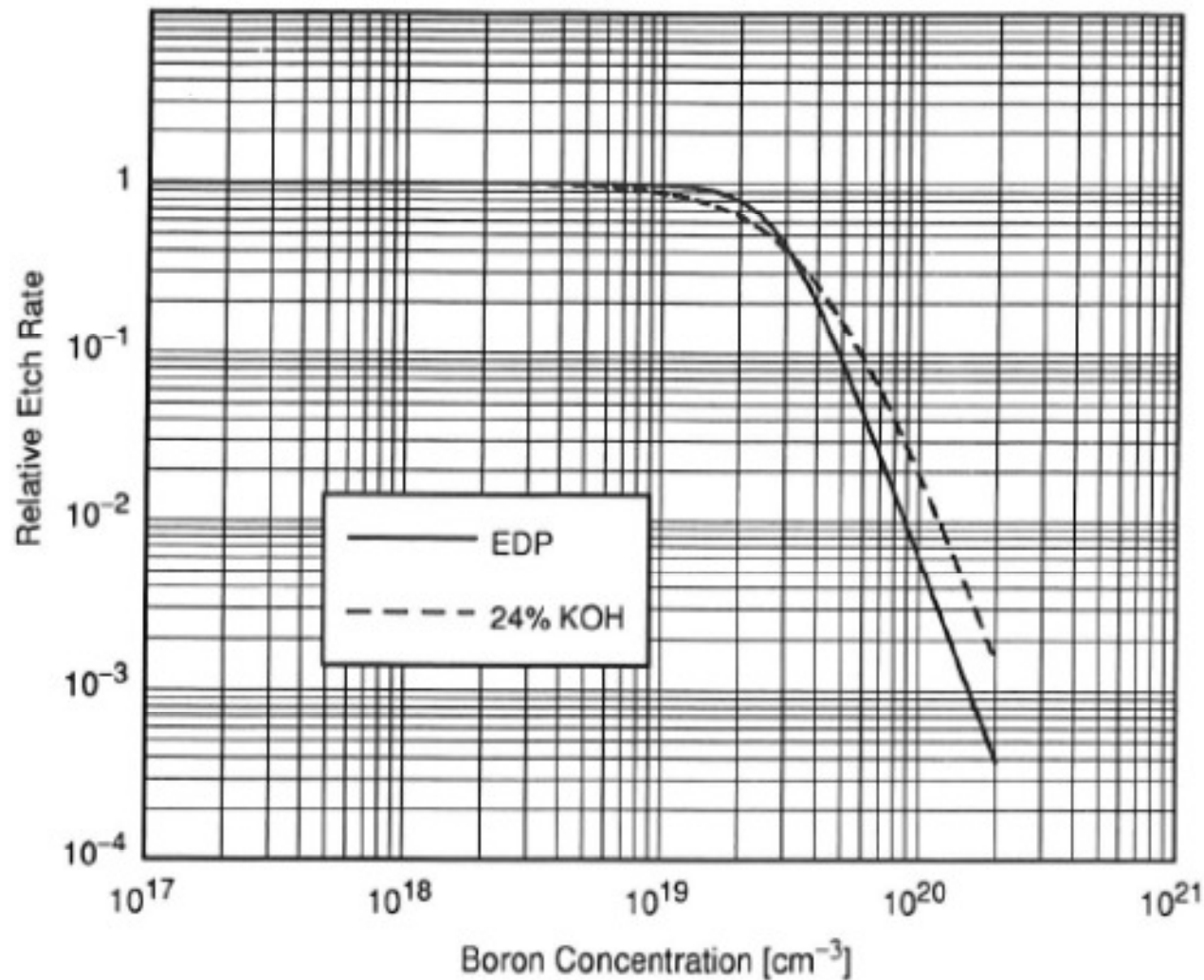
# ANISOTROPIC SILICON ETCHING

**TABLE 2** Experimentally Determined Activation Energies ( $E_a$ ) and Pre-exponential Factors ( $R_0$ ) for Etch Rate Calculation with the Arrhenius Equation:  $R = R_0 \exp(-E_a/kT)$

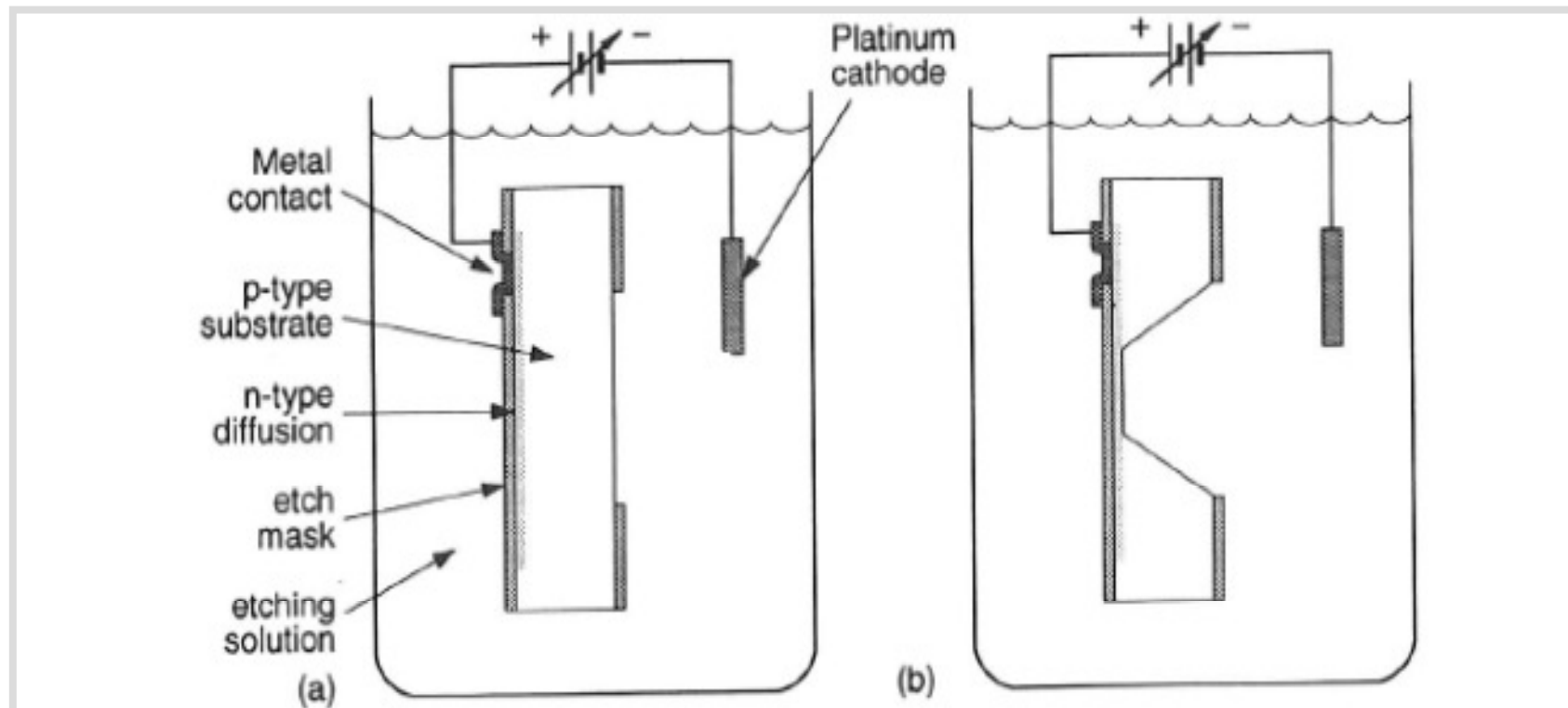
Etchants	$\langle 100 \rangle$ Si		$\langle 110 \rangle$ Si		SiO <sub>2</sub>	
	$E_a$ (eV)	$R_0$ ( $\mu\text{m h}$ )	$E_a$ (eV)	$R_0$ ( $\mu\text{m h}$ )	$E_a$ (eV)	$R_0$ ( $\mu\text{m h}$ )
Type-S EDP	0.40	$9.33 \times 10^6$	0.33	$1.16 \times 10^6$	0.80	$1.36 \times 10^8$
KOH, 20%	0.57	$1.23 \times 10^{10}$	0.59	$3.17 \times 10^{10}$	0.85	$3.52 \times 10^{11}$
a-KOH, 20%	0.62	$4.08 \times 10^{10}$	0.58	$4.28 \times 10^9$	0.90	$1.72 \times 10^{12}$
KOH, 34%	0.61	$3.10 \times 10^{10}$	0.60	$3.66 \times 10^{10}$	0.89	$2.34 \times 10^{12}$
NaOH, 24%	0.65	$1.59 \times 10^{11}$	0.68	$7.00 \times 10^{11}$	0.90	$3.20 \times 10^{12}$
LiOH, 10%	0.60	$3.12 \times 10^{10}$	0.62	$8.03 \times 10^{10}$	0.86	$2.34 \times 10^{11}$

a-KOH contains isopropyl alcohol at 250 ml/l

# ANISOTROPIC SILICON ETCHING



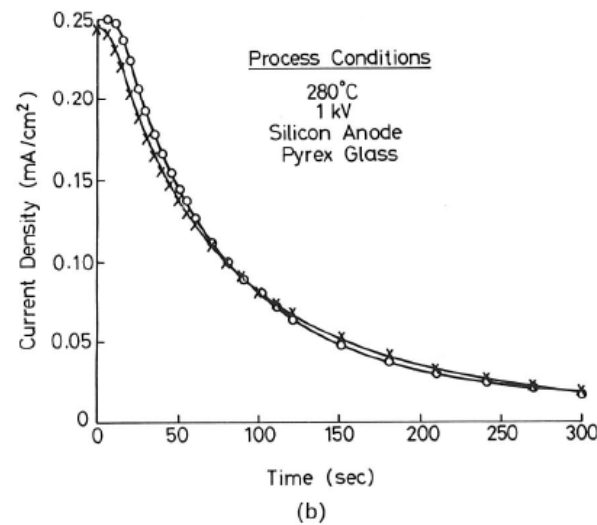
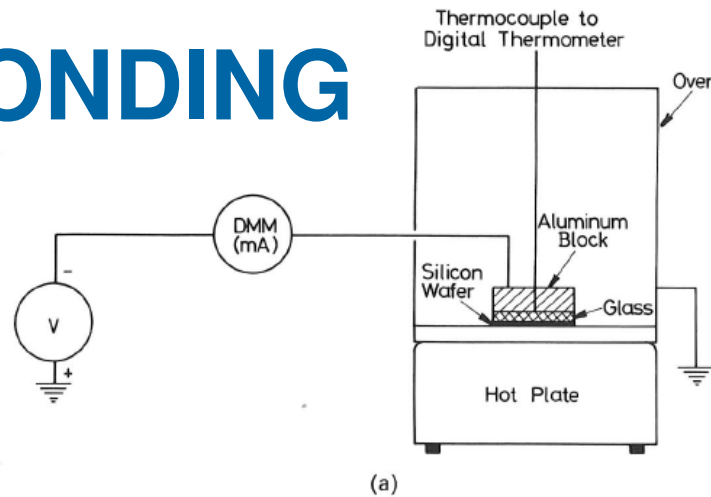
# ANISOTROPIC SILICON ETCHING



**Fig. 27** The electrochemical etch-stop technique used to form a diaphragm.

# WAFER BONDING

## Anodic bonding



**Fig. 28** (a) Schematic of an anodic bonding apparatus. The wafer assembly is pressed against a hot plate when the electric field is applied. (b) Typical current traces. The bond is complete when the current drops to about 10% of its peak value. (After Ref. 217)

# WAFER BONDING

## FUSION BONDING

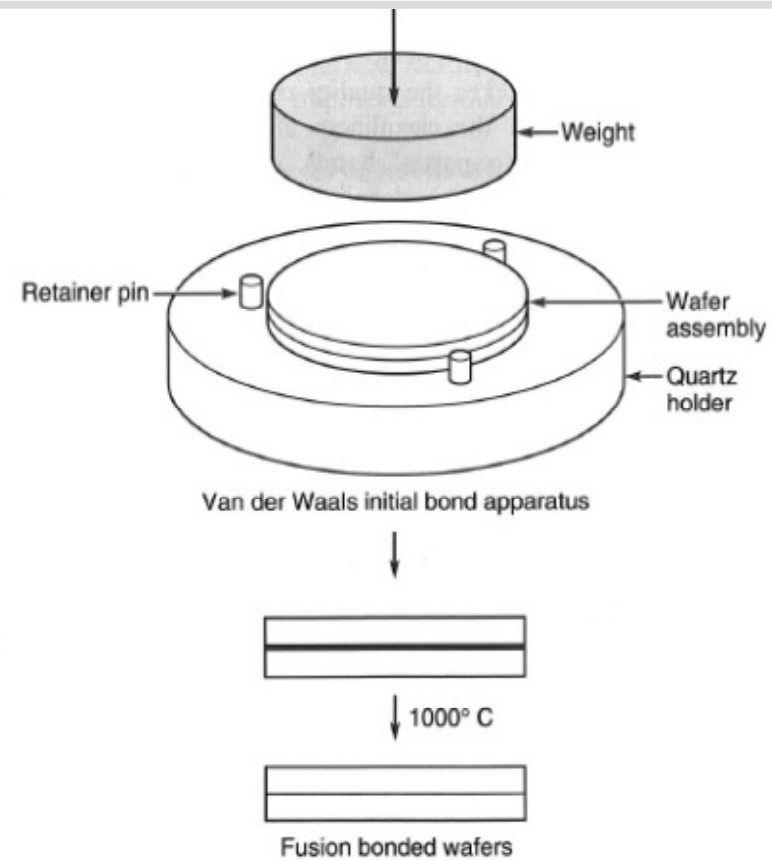
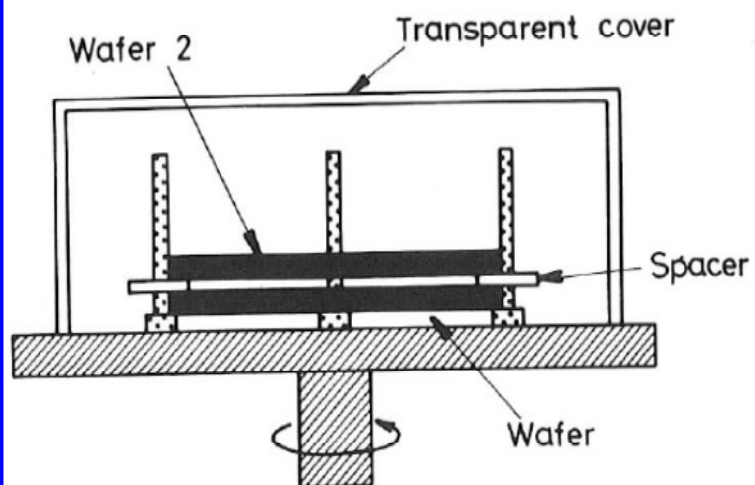
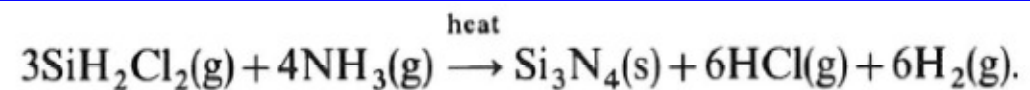


Fig. 29 Schematic of a fusion bonding apparatus. After pressing the wafers together, they are transferred to a high-temperature furnace to establish the bond.

# SURFACE MICROMACHINING

- THIN FILM MATERIALS

- Poly silicon
- Amorphous silicon
- Epitaxi silicon
- Silicon Nitride (LPCVD)
  - 300-500 MT 700-900 C



- Silicon dioxide

•Silicon  
dioxide

# SURFACE MICROMACHINING

- THIN FILM ETCHING

- Silicon dioxide

- Isotropic etching

- **DILUTED HF OR BUFFERED HF (BUFFERED WITH AMMONIUM-FLUORIDE)**

- Anisotropic etching

- **REACTIVE ION ETCHING (RIE)**

- » **1:1 C<sub>2</sub>F<sub>6</sub> and CHF<sub>3</sub>**

- Silicon nitride

- Isotropic etching

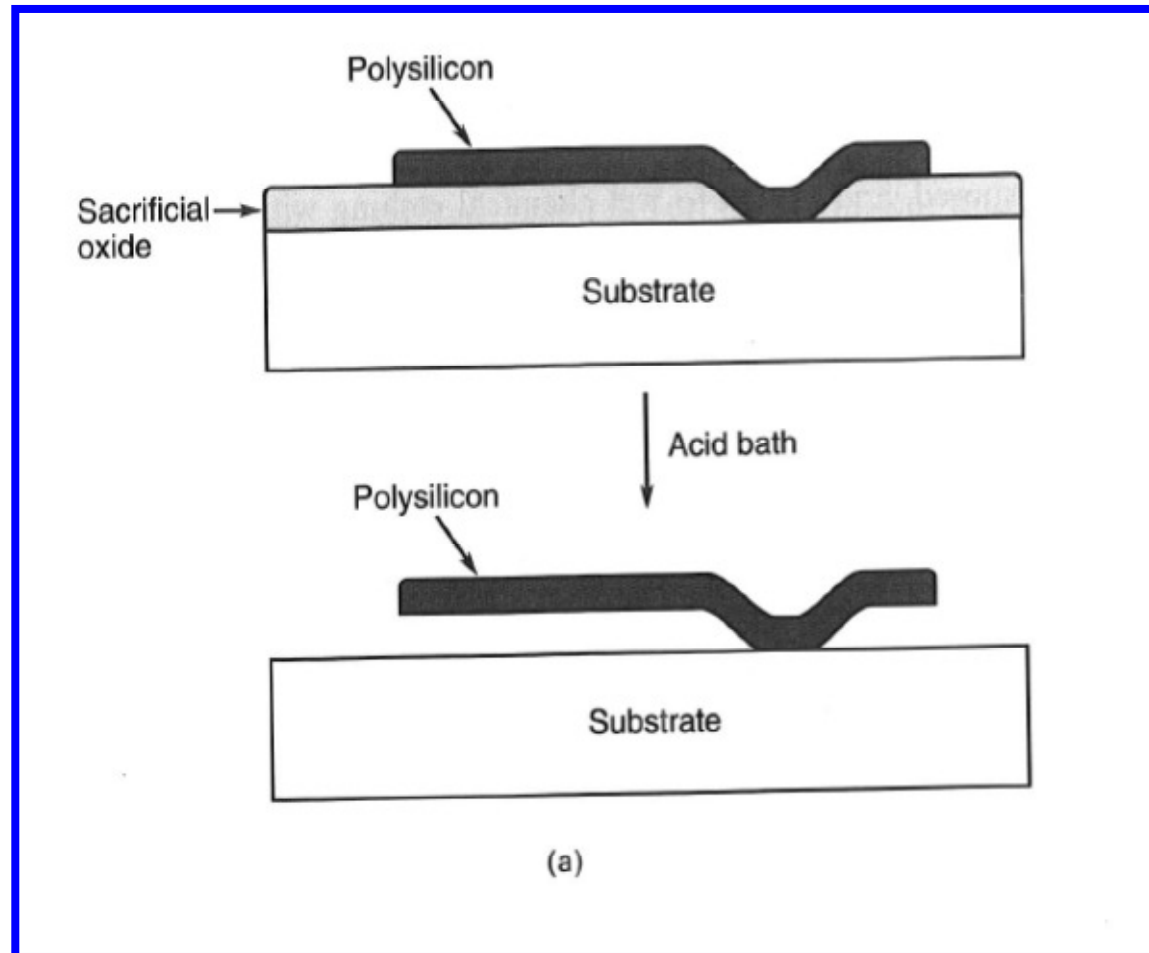
- » **H<sub>3</sub>PO<sub>4</sub> 140-200 C**

- Anisotropic etching *same as silicon dioxide*

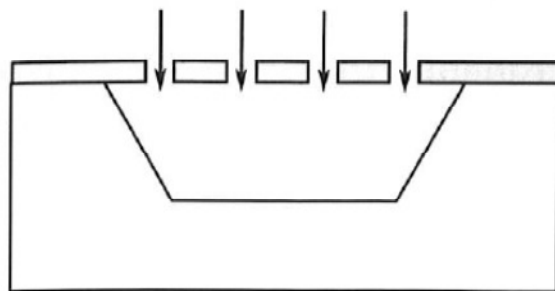
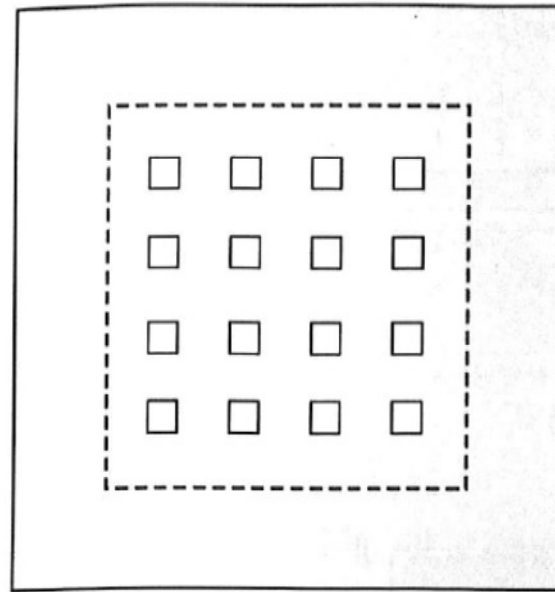


# SURFACE MICROMACHINING

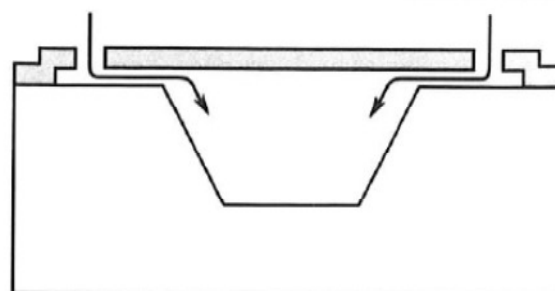
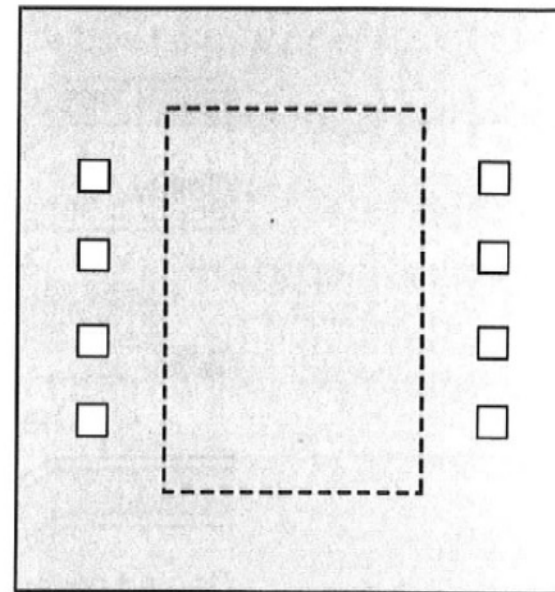
## Sacrificial etching



# SURFACE MICROMACHINING



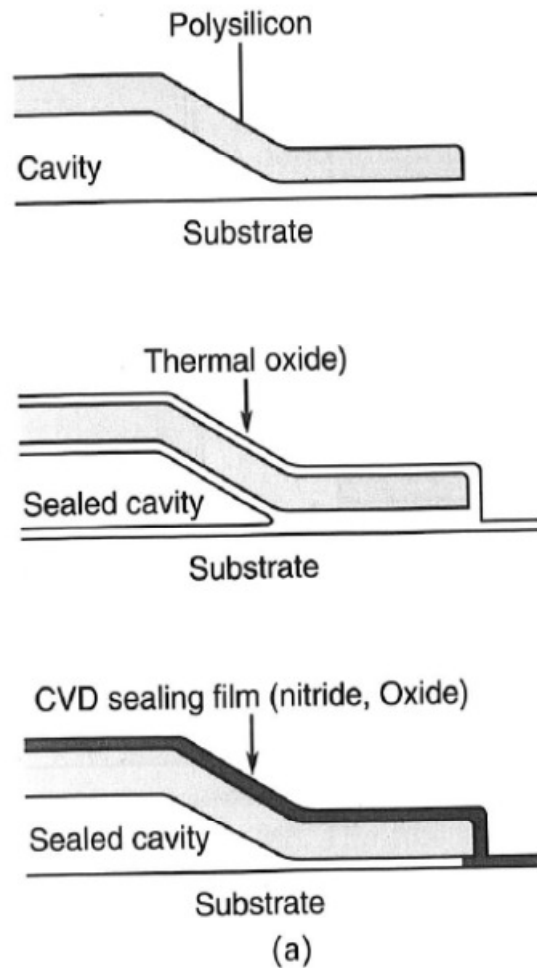
Vertical access



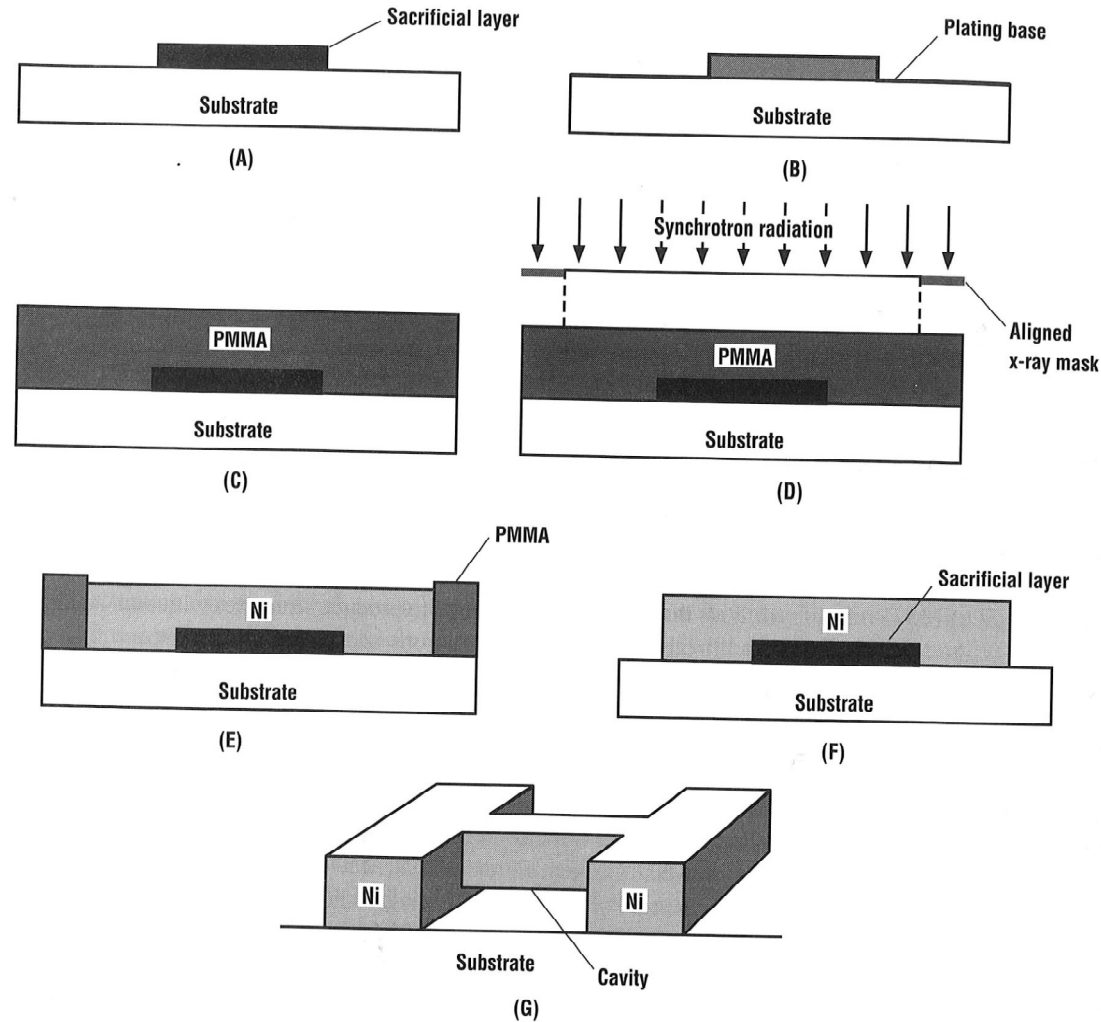
Horizontal access

# SURFACE MICROMACHINING

- Sealing

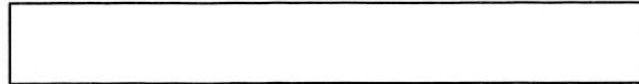


# LIGA

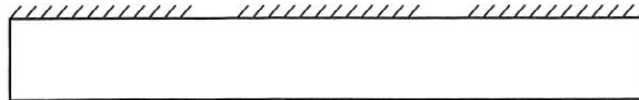


**Figure 19.34** Cross-sectional view of LIGA with sacrificial layers. (A) Pattern sacrificial layer; (B) sputter plating base; (C) deposit PMMA; (D) align x-ray mask and expose PMMA; (E) develop PMMA and electroplate Ni; (F) remove PMMA and plating base to clear access to the sacrificial layer; (G) etch sacrificial layer, thereby undercutting and freeing the Ni structure (from Guckel [75], © 1998 IEEE).

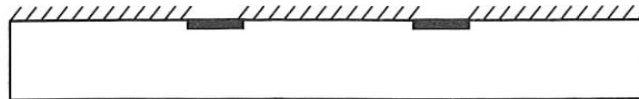
# EXAMPLES



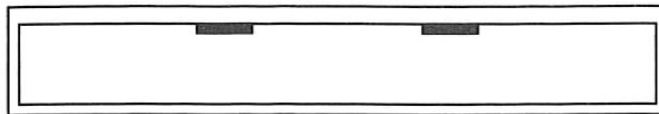
**Step 1: <100> silicon wafer**



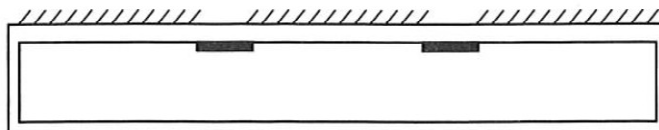
**Step 2: Mask 1 lithography process**



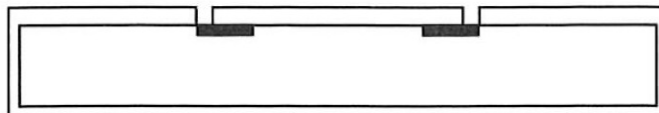
**Step 3: B<sup>+</sup> ion implantation**



**Step 4: Anneal and oxidation**



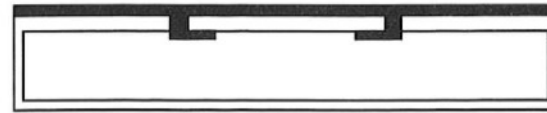
**Step 5: Mask 2 lithography**



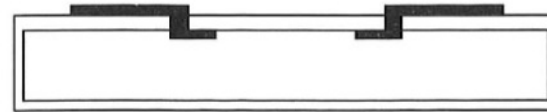
**Step 6: Contact etch**

# EXAMPLES

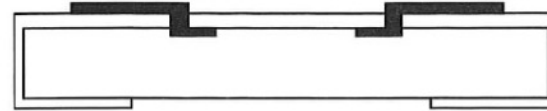
## Piezoresistive pressure sensor



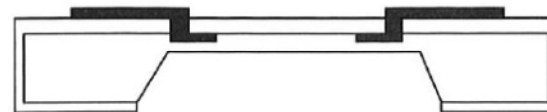
Step 7: Aluminum deposition



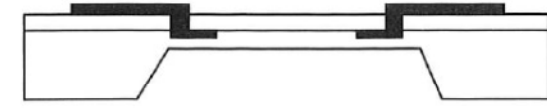
Step 8: Mask 3 lithography and aluminum etch



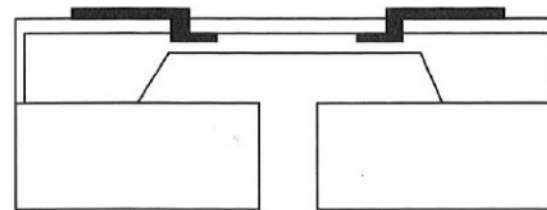
Step 9: Mask 4 lithography and silicon dioxide etch



Step 10: Anisotropic etch from backside of wafer



Step 11: Silicon dioxide etch

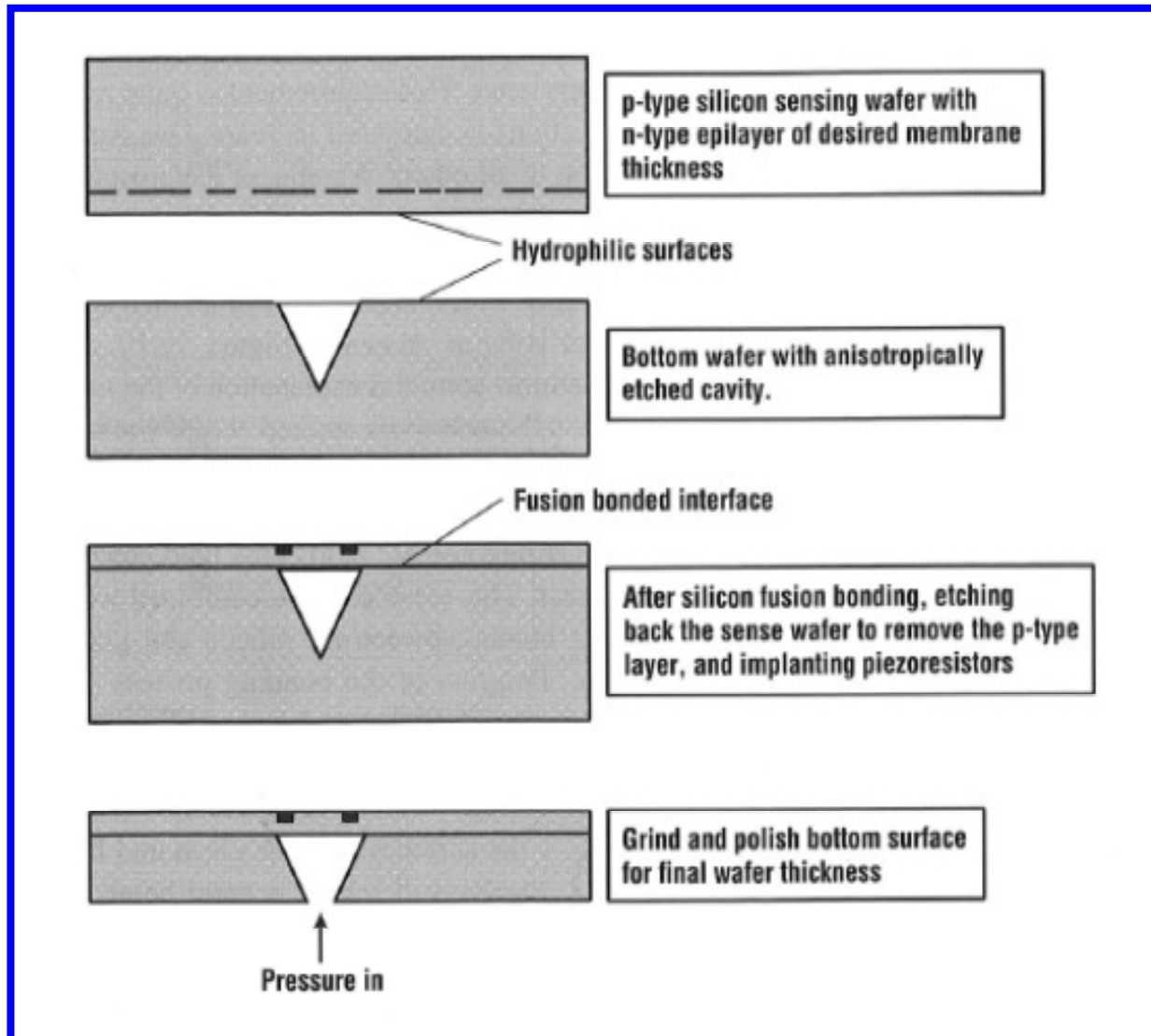


Step 12: Anodic bonding of glass substrate

**Figure 19.18** Bulk micromachining process for a piezoresistive pressure sensor.

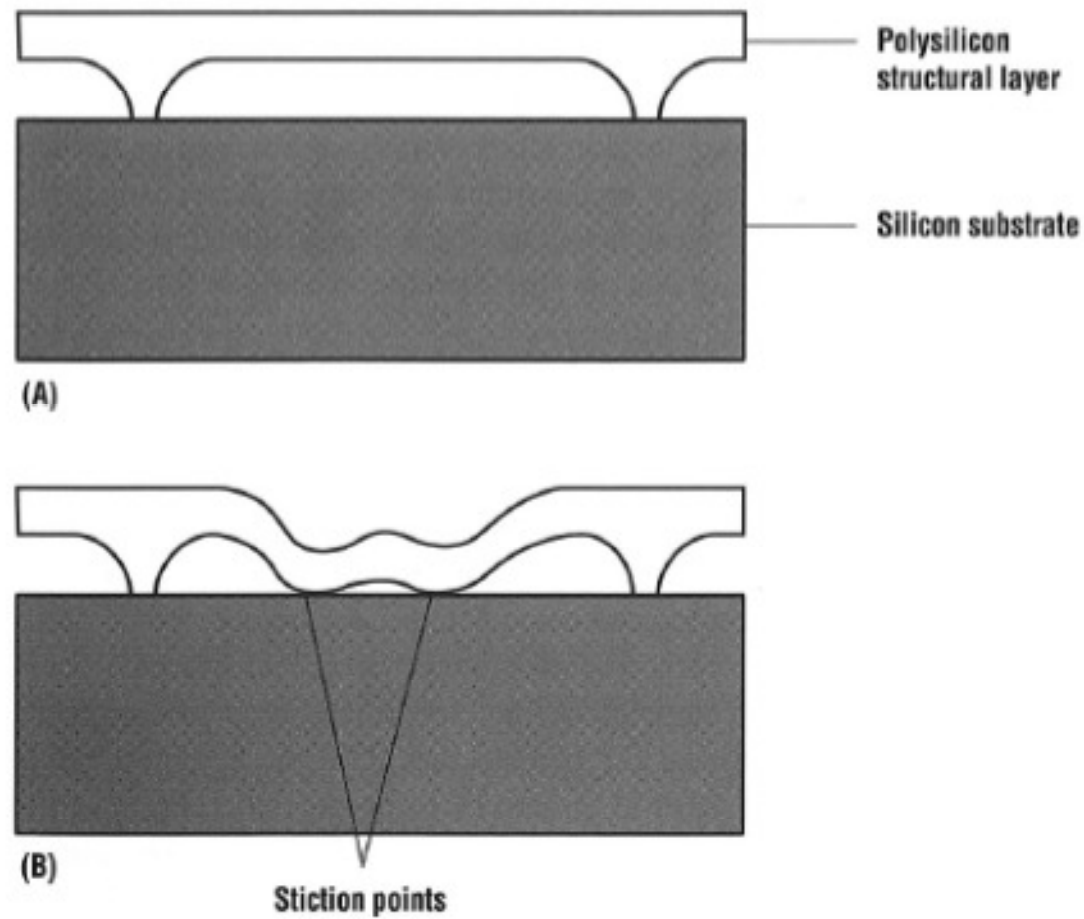
# EXAMPLES

## Piezoresistive pressure sensor



# EXAMPLES

Problem...



**Figure 19.25** Side view of a released structure (A) without and (B) with stiction at two points.

# EXAMPLES

Accelerometer

